

S3 Text: Neural Mass Models

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Neural Mass Models

The equations for the first cortical region are

$$\begin{aligned}
 v_i(1) &= [a_{12}s(\bar{v}_p(2)) + \gamma_3s(\tilde{v}_p(1))] \otimes h_e & (1) \\
 v_s(1) &= [u + \gamma_1s(\tilde{v}_p(1))] \otimes h_e \\
 v_{pe}(1) &= [a_{12}s(\bar{v}_p(2)) + \gamma_2s(\tilde{v}_s(1))] \otimes h_e \\
 v_{pi}(1) &= \gamma_4s(\tilde{v}_i(1)) \otimes h_i \\
 v_p(1) &= v_{pe}(1) - v_{pi}(1)
 \end{aligned}$$

and for the second region are

$$\begin{aligned}
 v_i(2) &= \gamma_3s(\tilde{v}_p(2)) \otimes h_e & (2) \\
 v_s(2) &= [a_{21}s(\bar{v}_p(1)) + \gamma_1s(\tilde{v}_p(2))] \otimes h_e \\
 v_{pe}(2) &= \gamma_2s(\tilde{v}_s(2)) \otimes h_e \\
 v_{pi}(2) &= \gamma_4s(\tilde{v}_i(2)) \otimes h_i \\
 v_p(2) &= v_{pe}(2) - v_{pi}(2)
 \end{aligned}$$

Parameters γ_1 to γ_4 denote within-unit or ‘intrinsic’ connection strengths. In these equations \tilde{v} denotes the potential after a delay τ_{ii} due to signalling delays among the different cell populations within a cortical region. Here we use a first order Taylor series, $\tilde{v} = v - \tau_{ii}\dot{v}$ to capture these within-region (or ‘intrinsic’) delays. Similarly, $\bar{v} = v - \tau_{ij}\dot{v}$ captures the ‘extrinsic’ delay, τ_{ij} , from region j to i .

Differential equations

Each synapse

$$v_{out}(t) = h_e(t) \otimes s(v_{in}(t)) \quad (3)$$

$$h_e(t) = \frac{H_e}{\tau_e} t \exp(-t/\tau_e) \quad (4)$$

can be implemented with a second order DE or two first order DEs [1]

$$\dot{v}_{out} = c_{out} \quad (5)$$

$$\dot{c}_{out} = \frac{H_e}{\tau_e} s(v_{in}) - \frac{2}{\tau_e} c_{out} - \frac{1}{\tau_e^2} v_{out} \quad (6)$$

where c_{out} is the current flowing through the synapse. Hence each synapse gives rise to two DEs. The convolution equations that define neural masses then become a set of differential equations. For a single cortical unit we have

$$\begin{aligned}
 \dot{v}_s &= c_s \\
 \dot{v}_{pe} &= c_{pe} \\
 \dot{v}_{pi} &= c_{pi} \\
 \dot{c}_s &= \frac{H_e}{\tau_e} \gamma_3(s(u) + \gamma_1 s(v_p)) - \frac{2}{\tau_e} c_s - \frac{1}{\tau_e^2} v_s \\
 \dot{c}_{pe} &= \frac{H_e}{\tau_e} \gamma_2 s(v_s) - \frac{2}{\tau_e} c_{pe} - \frac{1}{\tau_e^2} v_{pe} \\
 \dot{c}_{pi} &= \frac{H_i}{\tau_i} \gamma_4 s(v_i) - \frac{2}{\tau_i} c_{pi} - \frac{1}{\tau_i^2} v_{pi} \\
 \dot{v}_i &= c_i \\
 \dot{c}_i &= \frac{H_e}{\tau_e} \gamma_3 s(v_p) - \frac{2}{\tau_e} c_i - \frac{1}{\tau_e^2} v_i \\
 \dot{v}_p &= c_{pe} - c_{pi}
 \end{aligned} \tag{7}$$

References

1. Grimbert F, Faugeras O. Bifurcation analysis of Jansen's neural mass model. *Neural Comput.* 2006;18(12):3052–68.