

PPIs and DYNAMIC CAUSAL MODELING FOR fMRI

Based on slides from: Klaas Stephan, Hanneke den Ouden, & Andre Marreiros



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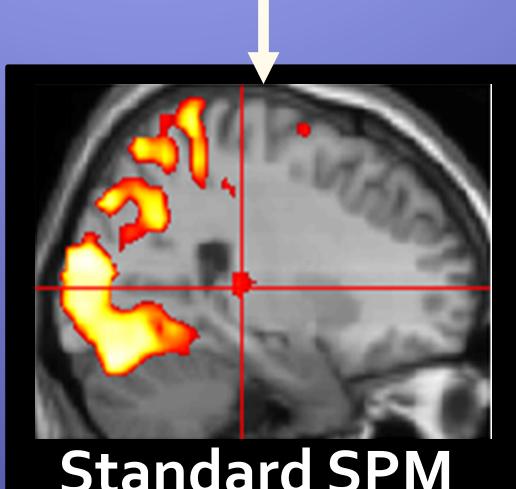
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Systems analysis in functional neuroimaging

Functional specialisation

- Analyses of regionally specific effects
- Which regions are specialized for a particular task?)
- Univariate analysis



Functional integration

- Analyses of inter-regional effects
- What are the interactions between the elements of a neuronal system?
- Univariate & Multivariate analysis

Functional connectivity

Effective connectivity

Systems analysis in functional neuroimaging

Functional integration

Functional connectivity

- Temporal correlations between spatially remote areas
- MODEL-FREE
- Exploratory
- Data Driven
- No Causation
- Whole brain connectivity

Effective connectivity

- The influence that one neuronal system exerts over another
- MODEL-DEPENDENT
- Confirmatory
- Hypothesis driven
- Causal (based on a model)
- Reduced set of regions

Connectivity Analysis Methods

- ◆ Functional Connectivity
 - ◆ ICA (independent component analyses)
 - ◆ Pairwise ROI Correlations
 - ◆ Whole brain seed driven connectivity
 - ◆ Graph analyses
- ◆ Effective Connectivity
 - ◆ PPI (psycho-physiological interactions)
 - ◆ SEM (structural equation models)
 - ◆ MAR (multivariate autoregressive models)
 - ◆ Granger Causality
 - ◆ DCM (dynamic causal models)

Psycho-physiological interaction (PPI)

- Bilinear model of how the psychological context **A** changes the influence of area **B** on area **C** :

$$B \times A \rightarrow C$$

- A PPI corresponds to differences in regression slopes for different contexts.

Psycho-physiological interaction (PPI)

		Task factor	
		Task A	Task B
Stimulus factor	Stim 1	A1	B1
	Stim 2	A2	B2

We can replace one main effect in the GLM by the time series of an area that shows this main effect.

GLM of a 2x2 factorial design:

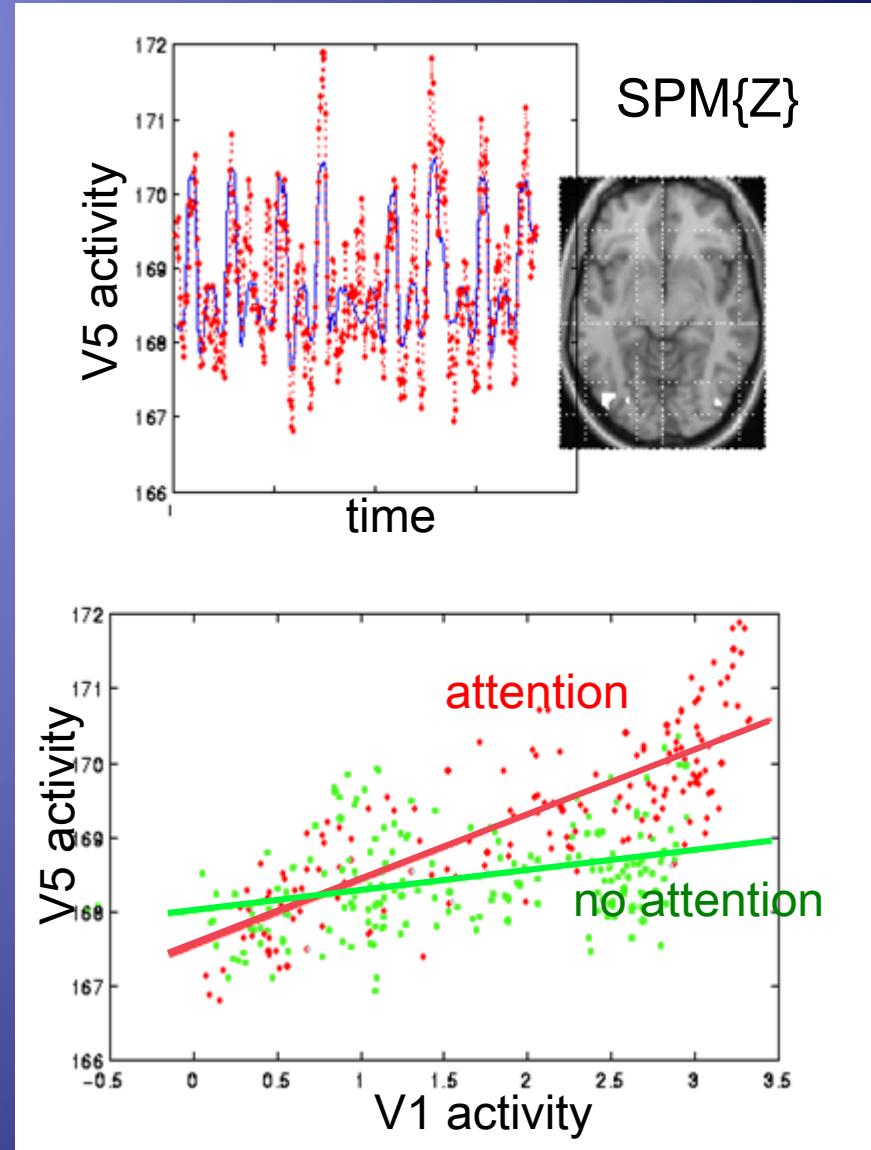
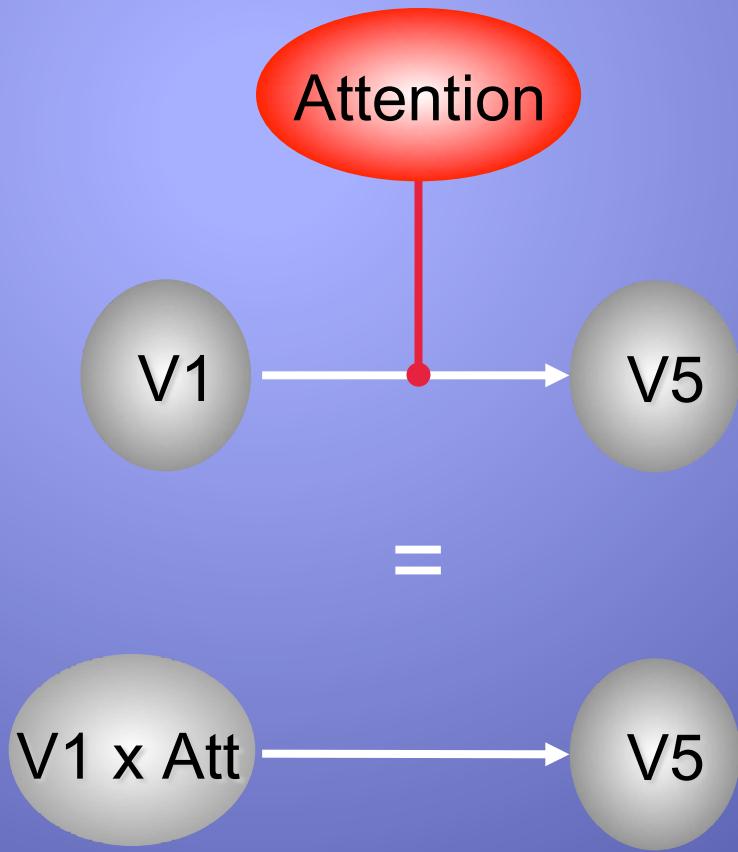
$$y = (T_A - T_B) \beta_1 + (S_1 - S_2) \beta_2 + (T_A - T_B)(S_1 - S_2) \beta_3 + e$$

main effect of task
main effect of stim. type
interaction

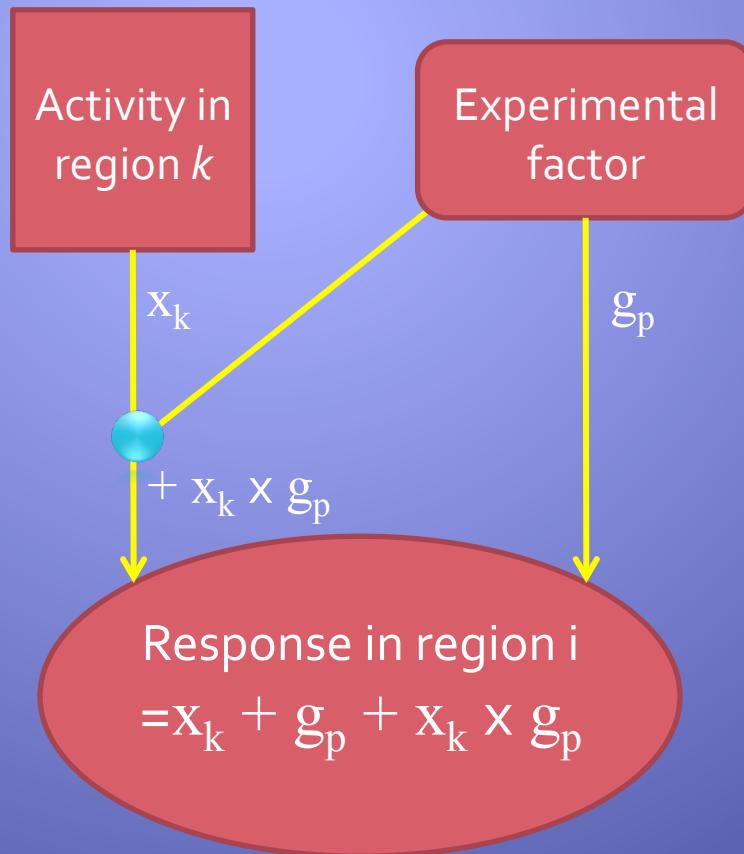
$$y = (T_A - T_B) \beta_1 + V1 \beta_2 + (T_A - T_B) V1 \beta_3 + e$$

main effect of task
V1 time series
≈ main effect of stim. type
psycho-physiological interaction

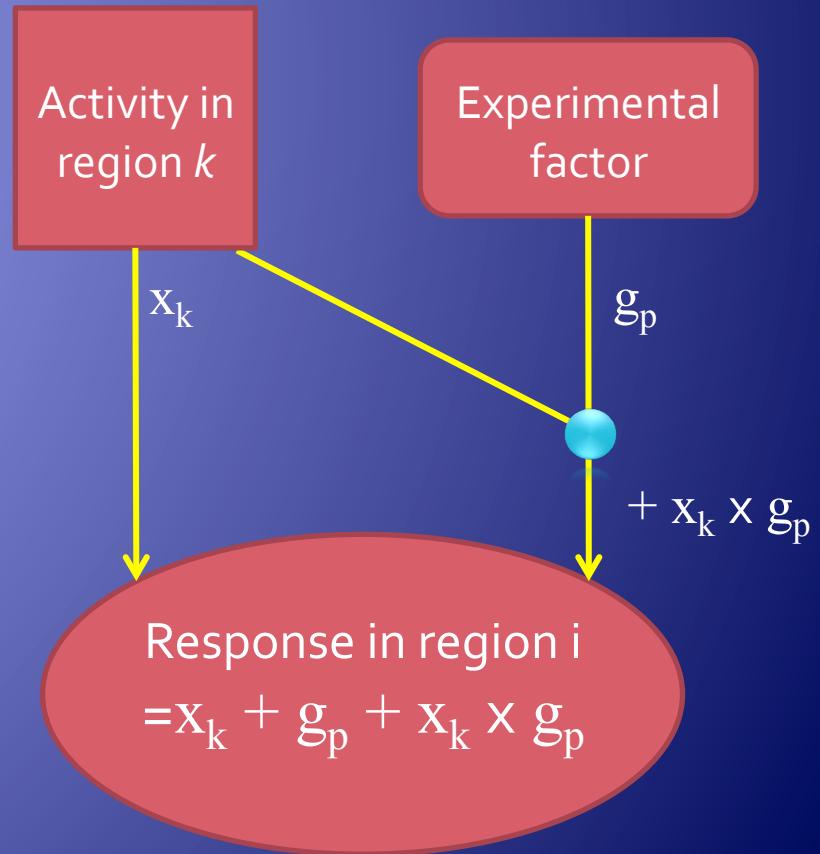
Attentional modulation of V1→V5



Two mechanistic interpretations of PPI's.



Context specific modulation
of responses to stimulus



Stimulus related modulation of
responses to context (attention)

PPI directionality



- ◆ Although PPIs select a source and find target regions, they cannot determine the directionality of connectivity.
- ◆ The regression equations are reversible. The slope of $A \rightarrow B$ is the reciprocal of $B \rightarrow A$.
- ◆ Directionality should be pre-specified and based on knowledge of anatomy or other experimental results.

PPI vs. correlation

- ◆ Are PPI's the same as correlations?
 - ◆ No
 - ◆ PPI's are based on regressions and assume a dependent and an independent variable
 - ◆ PPI's explicitly discount main effects

PPI vs. correlation

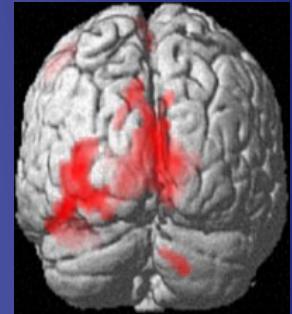
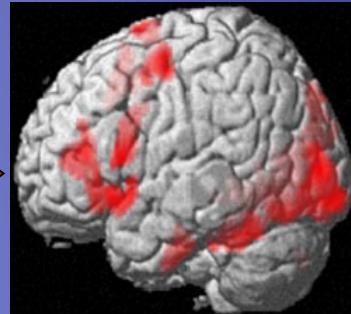
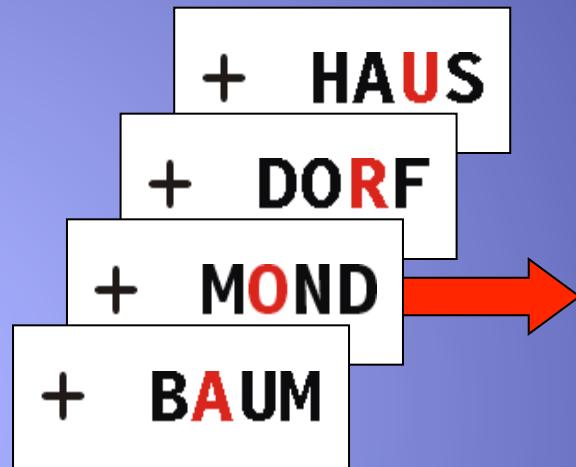
- ◆ Kim and Horwitz investigated connectivity using correlations vs. PPI regression applied to a biologically plausible neural model.
- ◆ PPI results were similar to those based on integrated synaptic activity (gold standard)
- ◆ Results from correlations were not significant for many of the [true] functional connections.
- ◆ A change in influence between 2 regions may not involve a change in signal correlation

PPI: summary

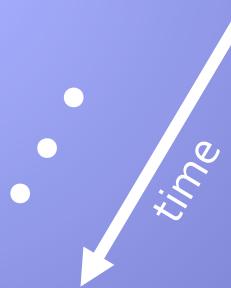
- ◆ Psychological interaction
 - ◆ Change in regression slope due to the differential response to a stimulus under the influence of different experimental contexts.
- ◆ Physiophysiological interaction
 - ◆ Change in regression slope due to the differential response to the signal from one region under the influence of another (region).
- ◆ Psychophysiological interaction
 - ◆ Change in regression slope due to the differential response to the signal from one region under the influence of different experimental contexts.

Task-driven lateralisation

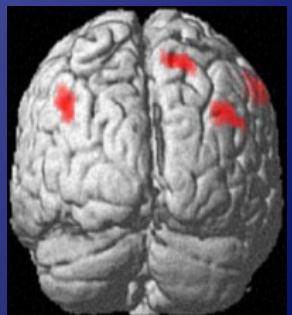
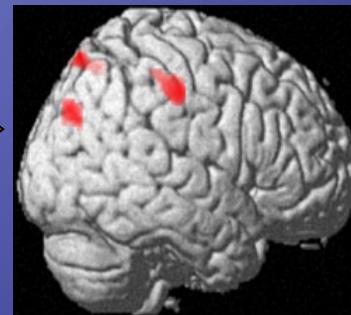
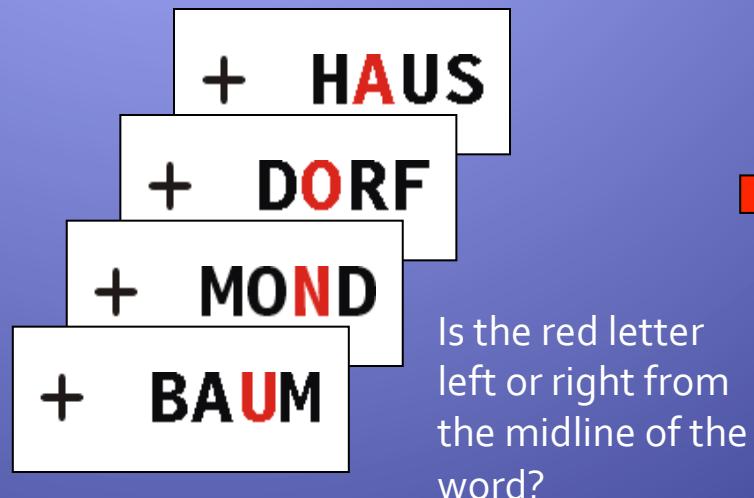
Does the word contain the letter A or not?



letter decisions > spatial decisions

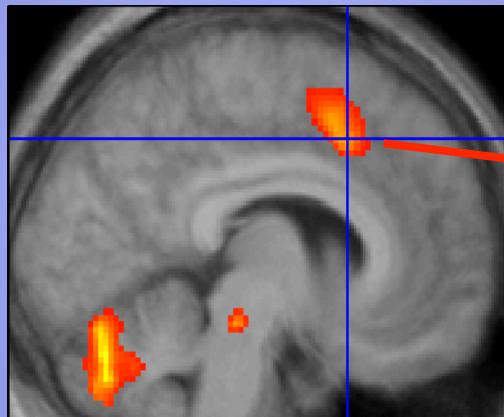


group analysis (random effects),
n=16, p<0.05 corrected
analysis with SPM2



spatial decisions > letter decisions

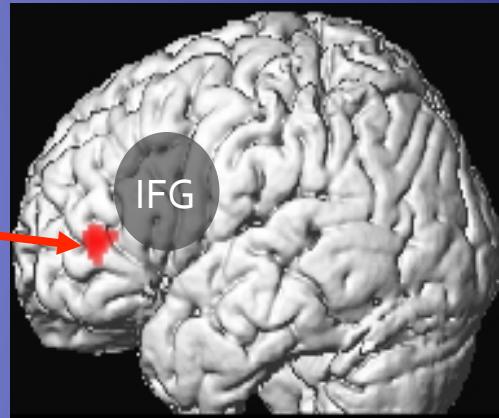
Bilateral ACC activation in both tasks – but asymmetric connectivity !



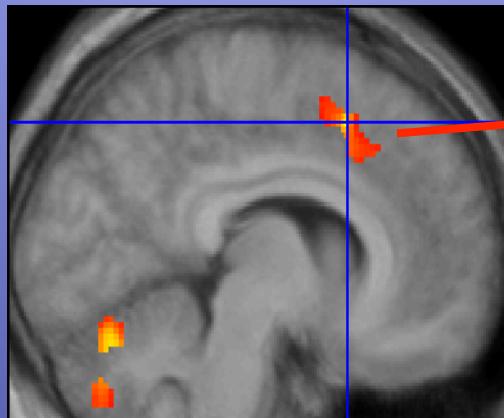
left ACC (-6, 16, 42)

group analysis
random effects (n=15)
 $p < 0.05$, corrected (SVC)

letter vs spatial
decisions

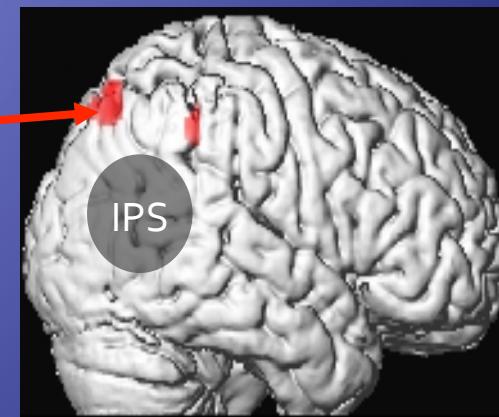


Left ACC → left inf. frontal gyrus (IFG):
increase during letter decisions.



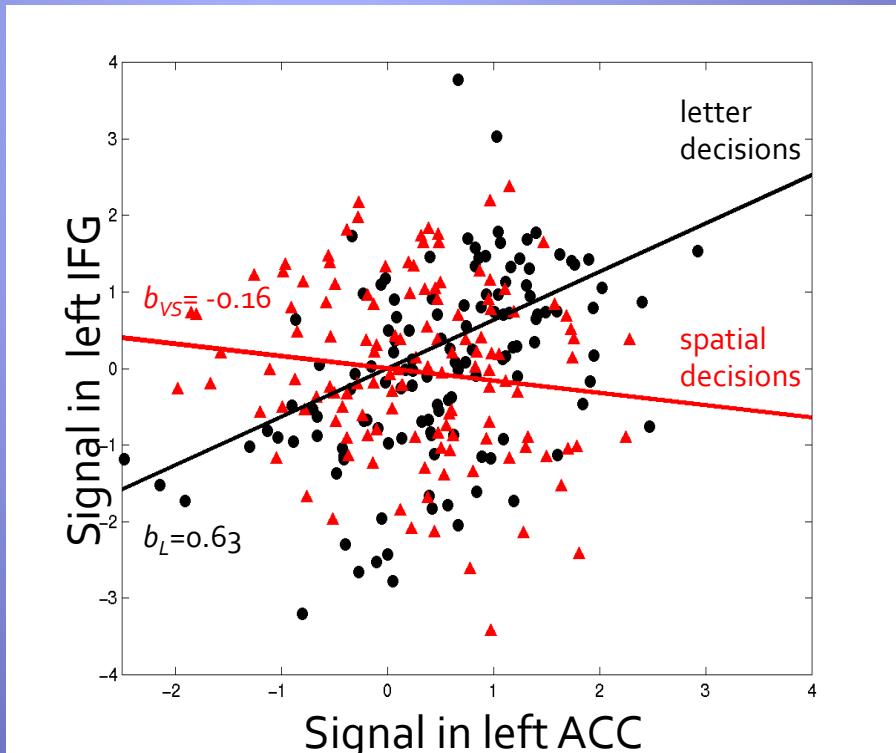
right ACC (8, 16, 48)

spatial vs letter
decisions

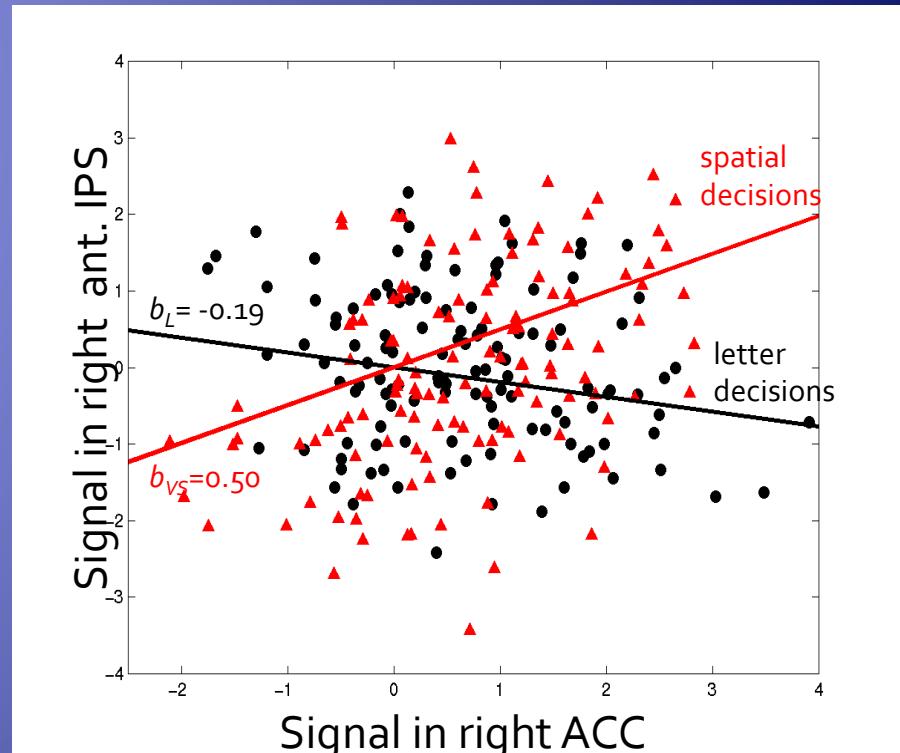


Right ACC → right IPS:
increase during spatial decisions.

PPI single-subject example



Left ACC signal plotted against left IFG



Right ACC signal plotted against right IPS

PPI: Pros

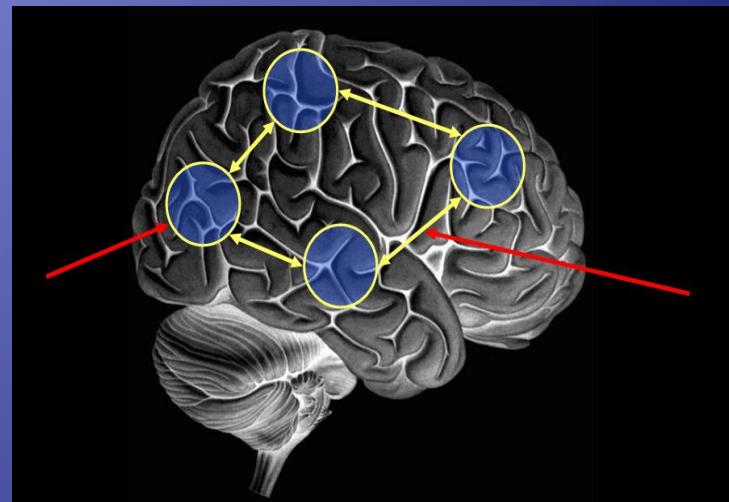
- ◆ Pros:
 - ◆ Given a single source region, we can test for its context-dependent connectivity across the entire brain
 - ◆ Easy to implement

PPI: Pros / Cons

- ◆ Cons:
 - ◆ Depend on factorial designs. If the interaction and main effects are not orthogonal, the sensitivity will be low.
 - ◆ Analysis can be overly sensitive to the choice of region.
 - ◆ Very simplistic model: i.e., contributions from a single area
 - ◆ Ignores time-series properties of data
 - ◆ Operates at the level of BOLD time series (spm99/2). SPM 5/8 deconvolves the BOLD signal to form the proper interaction term, and then reconvolves it.
 - ◆ Need DCM for to make robust statements about effective connectivity and causality.

Dynamic Causal Modeling

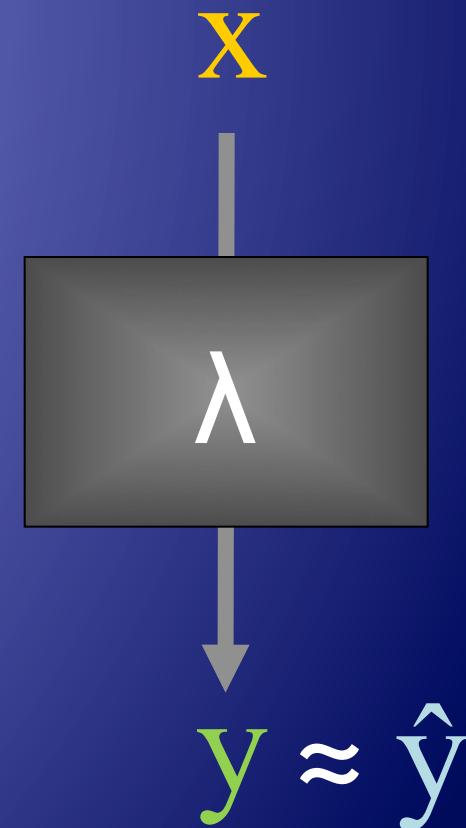
- ◆ DCM allows us to look at how areas within a network interact:
- ◆ Investigate functional integration & modulation of specific cortical pathways



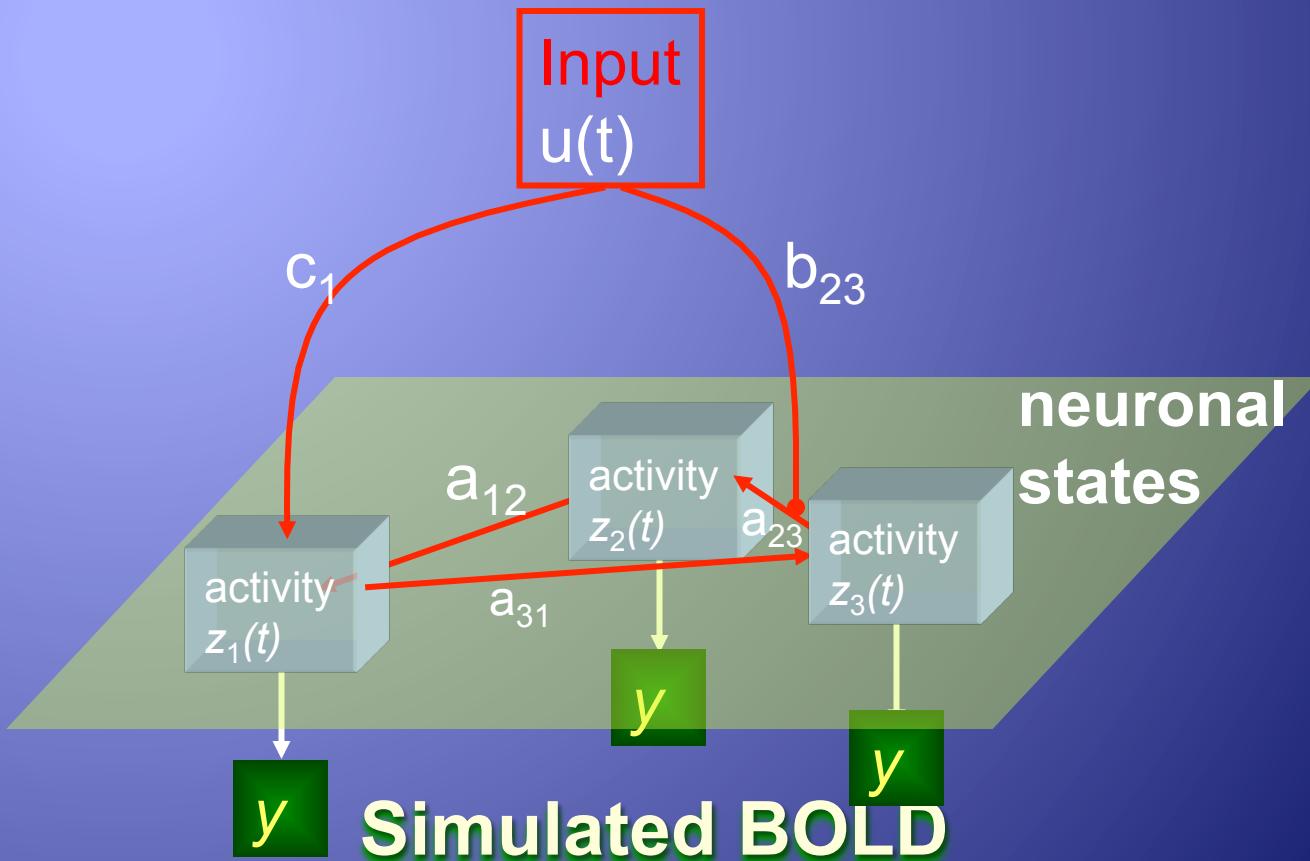
Principles of DCM:

- ◆ Investigate functional integration & modulation of specific cortical pathways
- ◆ Using a bilinear state equation, a cognitive system is modeled at its underlying neuronal level (which is not directly accessible to fMRI).
- ◆ The modeled neuronal dynamics (x) are transformed into area-specific 'simulated' BOLD signals (y) by a hemodynamic model (λ).

The aim of DCM is to estimate parameters at the “neuronal level” such that the modeled and measured BOLD signals are maximally* similar.



Conceptual overview



Use differential equations to represent a neuronal system

- ***State vector***
 - Changes with time
- ***Rate of change of state vector***
 - Interactions between elements
 - External inputs, u
- ***System parameters* θ**

$$z(t) = \begin{bmatrix} z_1(t) \\ \vdots \\ z_n(t) \end{bmatrix}$$

system represented by state variables

$$\begin{bmatrix} \dot{z}_1 \\ \vdots \\ \dot{z}_n \end{bmatrix} = \begin{bmatrix} f_1(z_1 \dots z_n, u, \theta_1) \\ \vdots \\ f_n(z_1 \dots z_n, u, \theta_n) \end{bmatrix}$$

$$\dot{z} = f(z, u, \theta)$$

DCM parameters = rate constants

Generic solution to the ODEs in DCM:

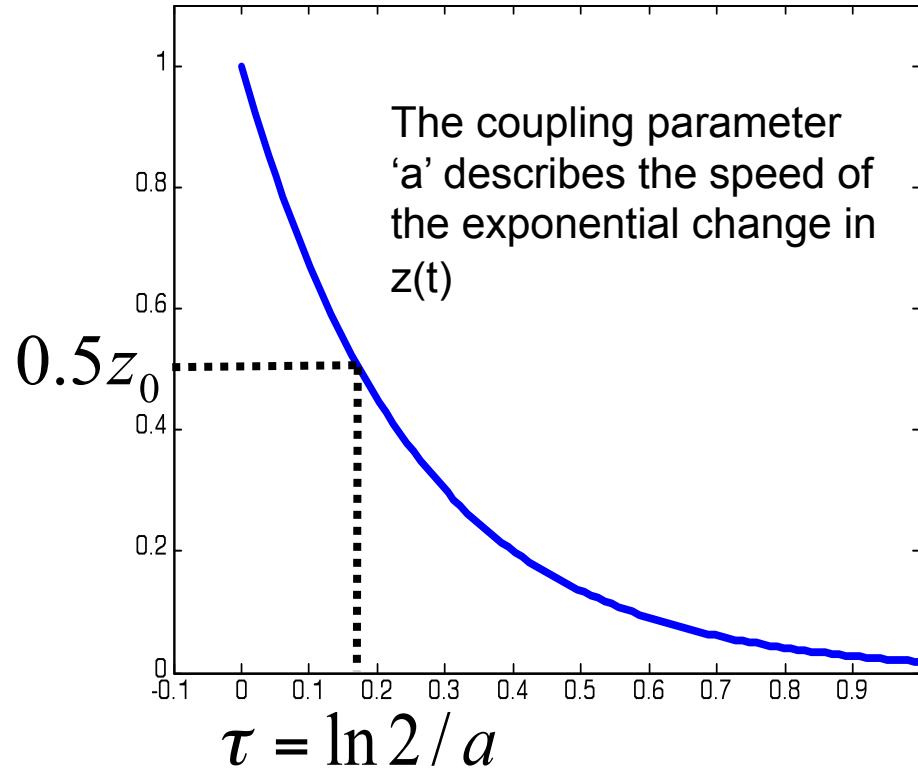
$$\frac{dz}{dt} = az \quad \longrightarrow \quad z(t) = z_0 \exp(at)$$

Coupling parameter 'a' is inversely proportional to the half life τ of $z(t)$:

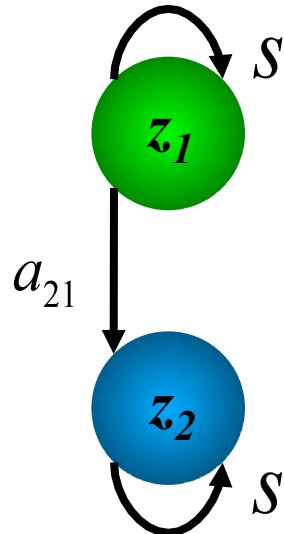
Half-life τ :

$$z(\tau) = 0.5z_0 \\ = z_0 \exp(a\tau)$$

$$\longrightarrow a = \ln 2 / \tau$$



Linear dynamics: 2 nodes



$$\dot{z}_1 = -sz_1$$

$$\dot{z}_2 = s(a_{21}z_1 - z_2)$$

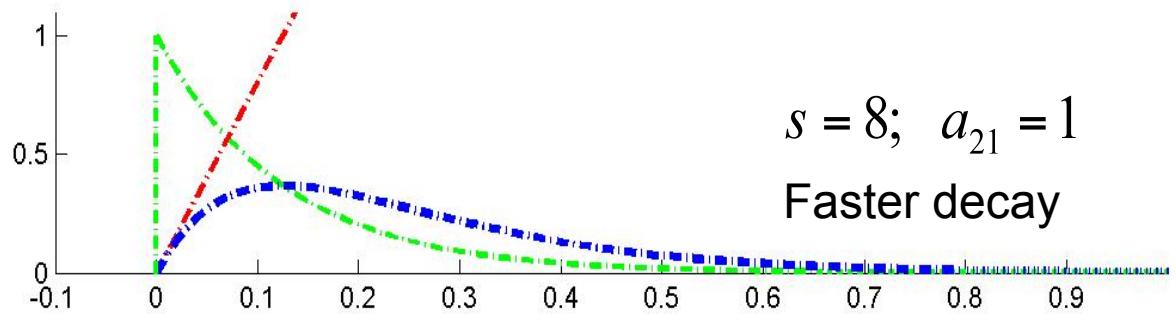
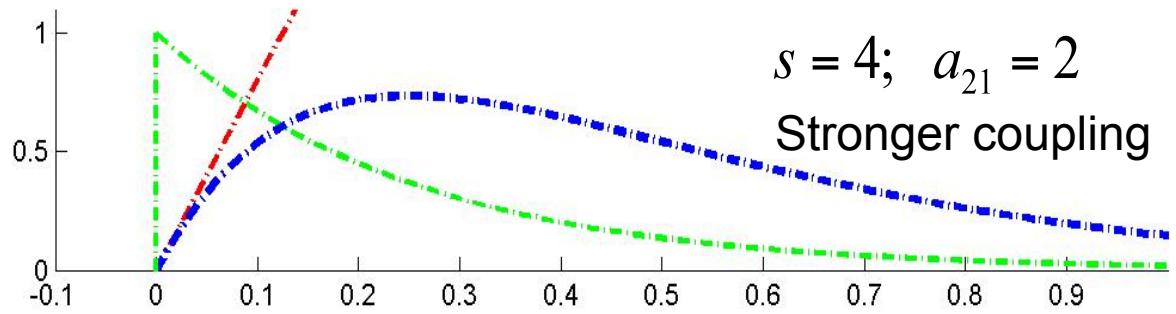
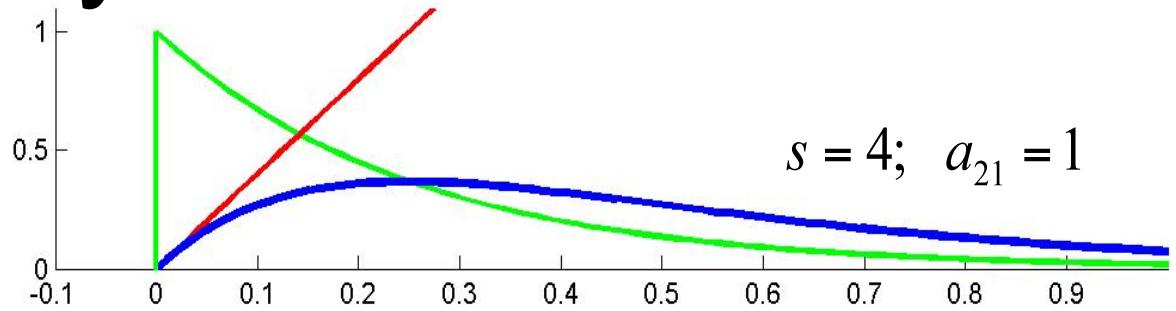
$$z_1(0) = 1$$

$$z_2(0) = 0$$

$$z_1(t) = \exp(-st)$$

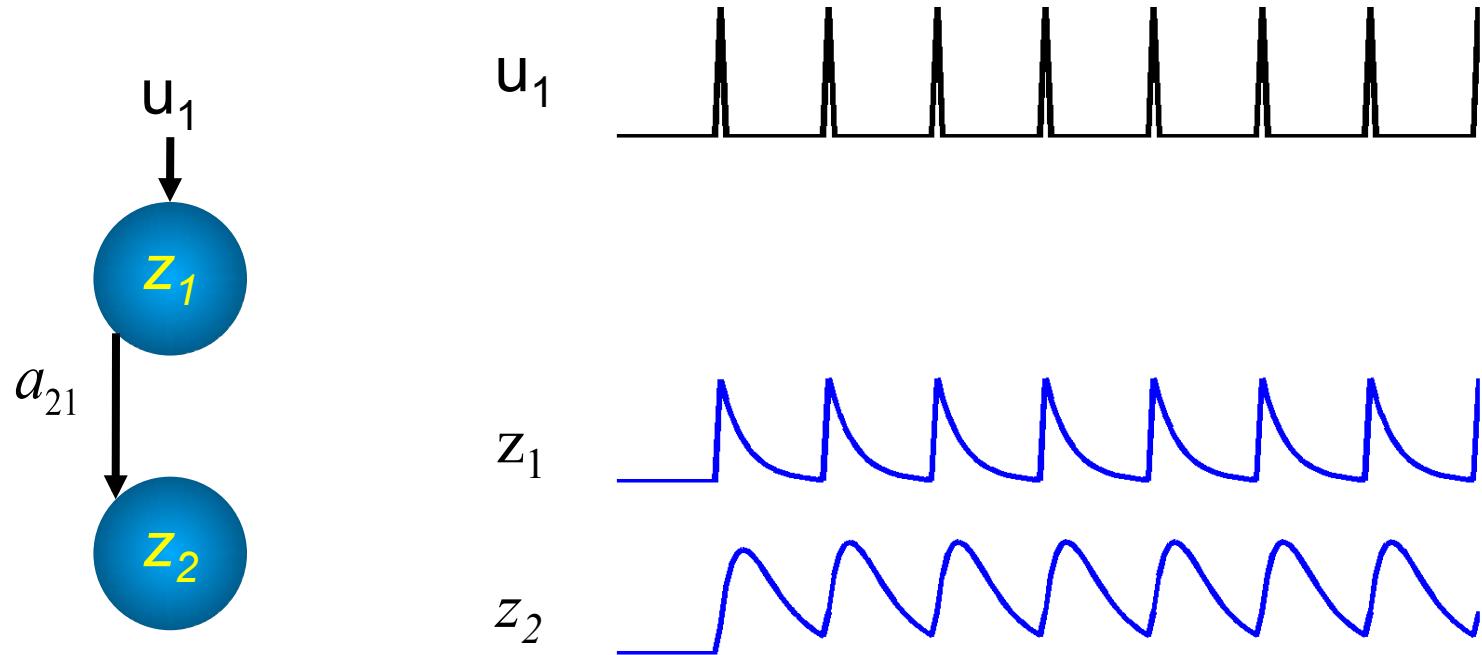
$$z_2(t) = sa_{21}t \exp(-st)$$

$$a_{21} > 0$$



— z_1	— $sa_{21}t$	— z_2
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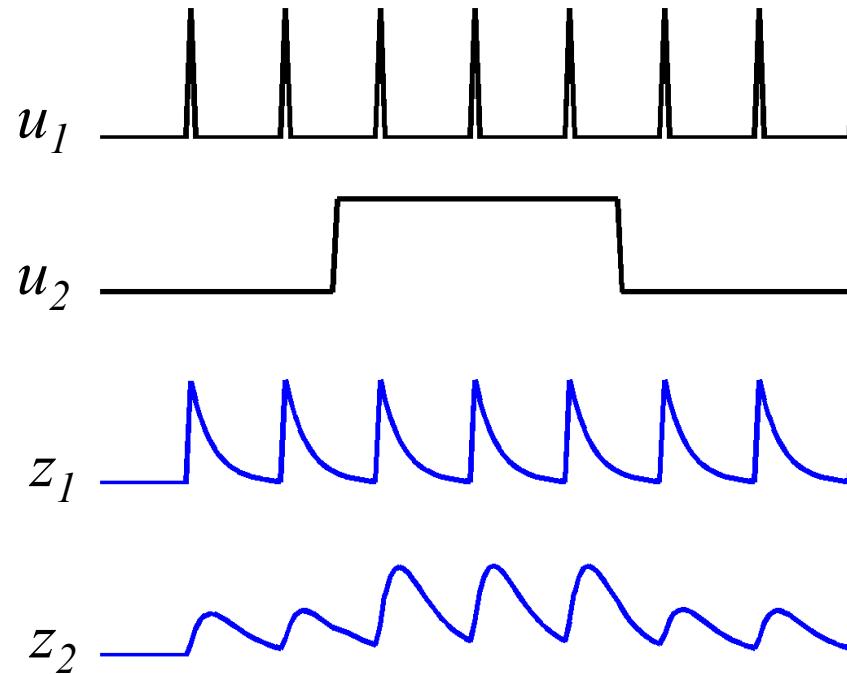
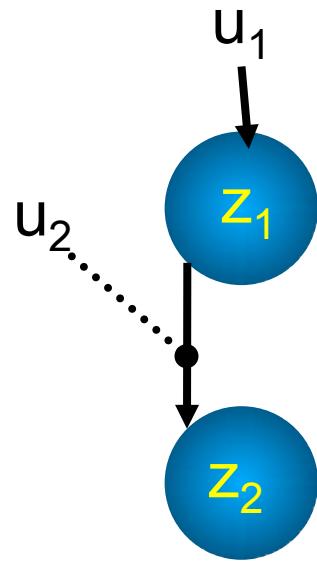
Neurodynamics: 2 nodes with input



$$\begin{bmatrix} \dot{z}_1 \\ \dot{z}_2 \end{bmatrix} = s \begin{bmatrix} -1 & 0 \\ a_{21} & -1 \end{bmatrix} \begin{bmatrix} z_1 \\ z_2 \end{bmatrix} + \begin{bmatrix} c \\ 0 \end{bmatrix} u_1 \quad a_{21} > 0$$

activity in z_2 is coupled to z_1 via coefficient a_{21}

Neurodynamics: positive modulation



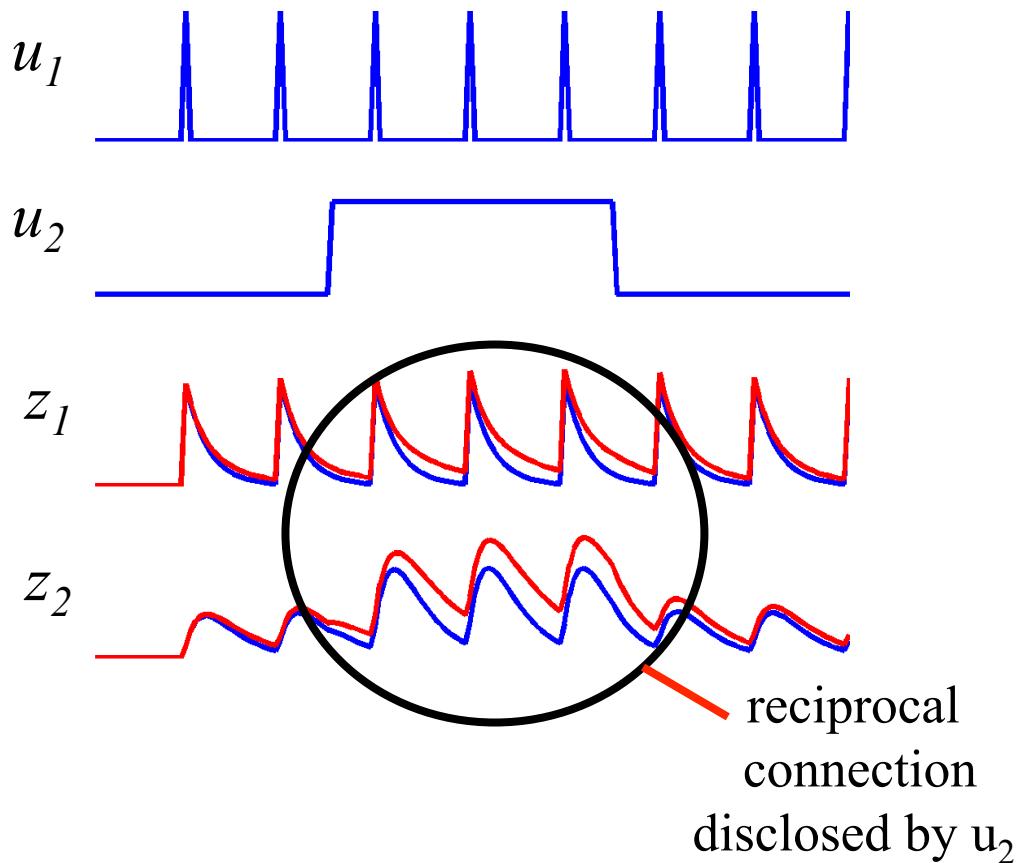
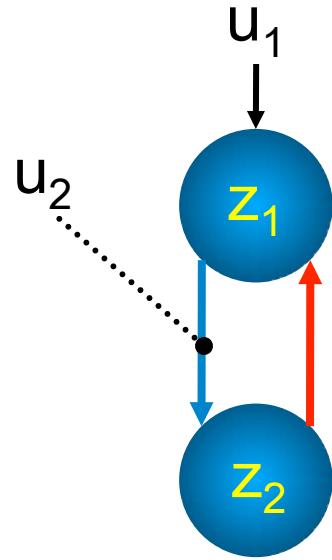
$$\begin{bmatrix} \dot{z}_1 \\ \dot{z}_2 \end{bmatrix} = s \begin{bmatrix} -1 & 0 \\ a_{21} & -1 \end{bmatrix} \begin{bmatrix} z_1 \\ z_2 \end{bmatrix} + u_2 \begin{bmatrix} 0 & 0 \\ b_{21}^2 & 0 \end{bmatrix} \begin{bmatrix} z_1 \\ z_2 \end{bmatrix} + \begin{bmatrix} c \\ 0 \end{bmatrix} u_1$$

index, not squared

$$b_{21}^2 > 0$$

modulatory input u_2 activity through the coupling a_{21}

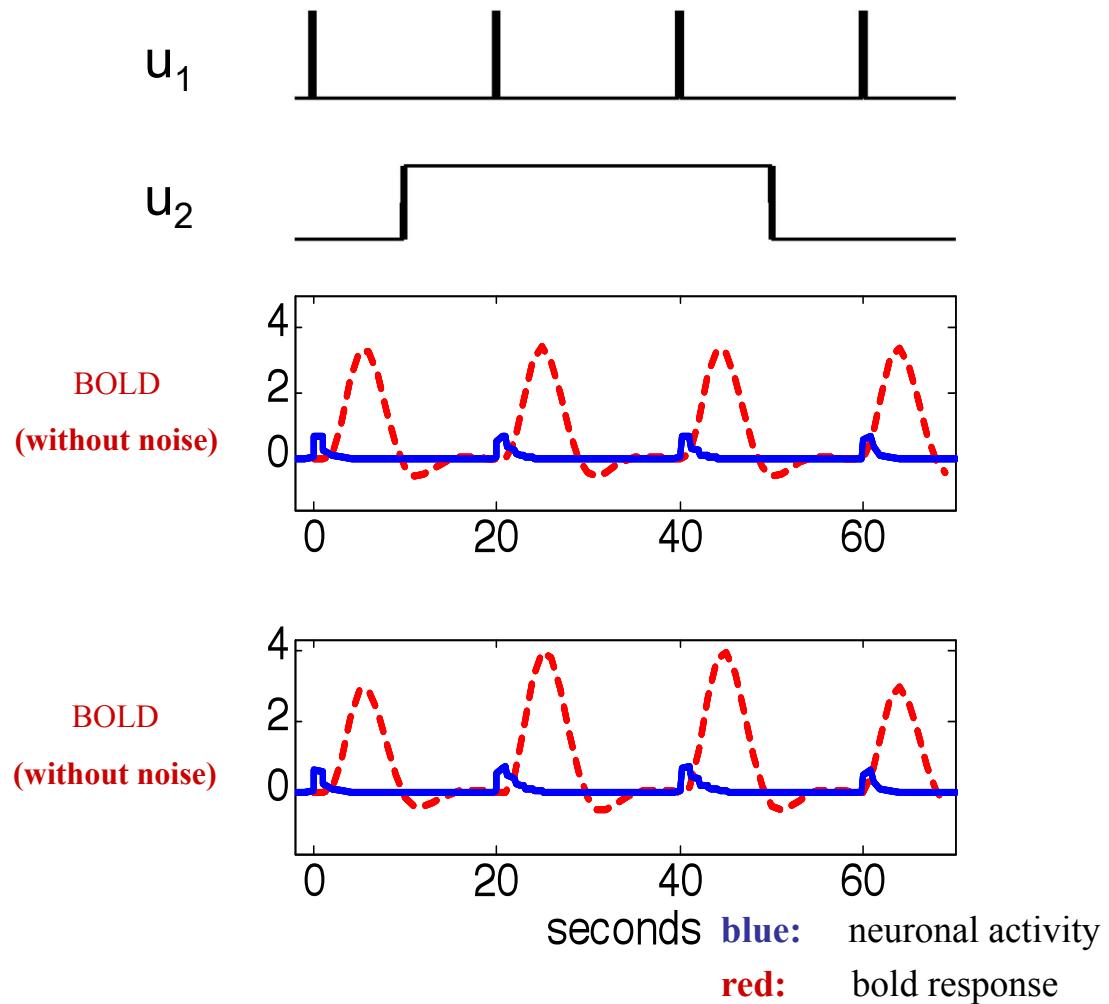
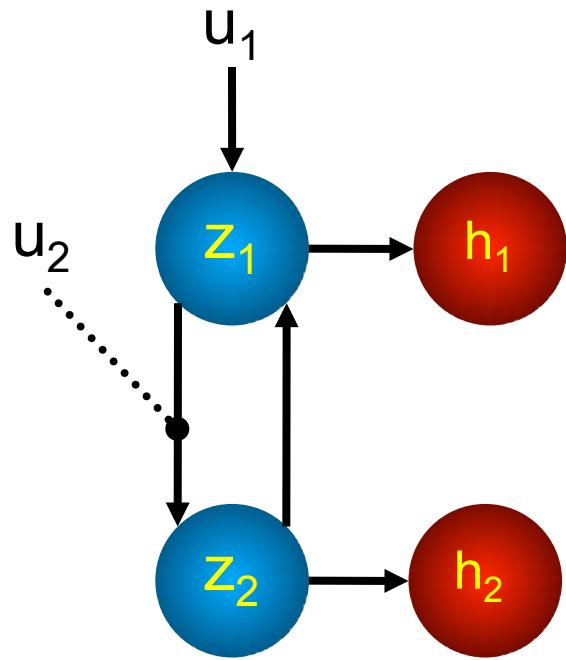
Neurodynamics: reciprocal connections



$$\begin{bmatrix} \dot{z}_1 \\ \dot{z}_2 \end{bmatrix} = s \begin{bmatrix} -1 & a_{12} \\ a_{21} & -1 \end{bmatrix} \begin{bmatrix} z_1 \\ z_2 \end{bmatrix} + u_2 \begin{bmatrix} 0 & 0 \\ b_{21}^2 & 0 \end{bmatrix} \begin{bmatrix} z_1 \\ z_2 \end{bmatrix} + \begin{bmatrix} c \\ 0 \end{bmatrix} u_1$$

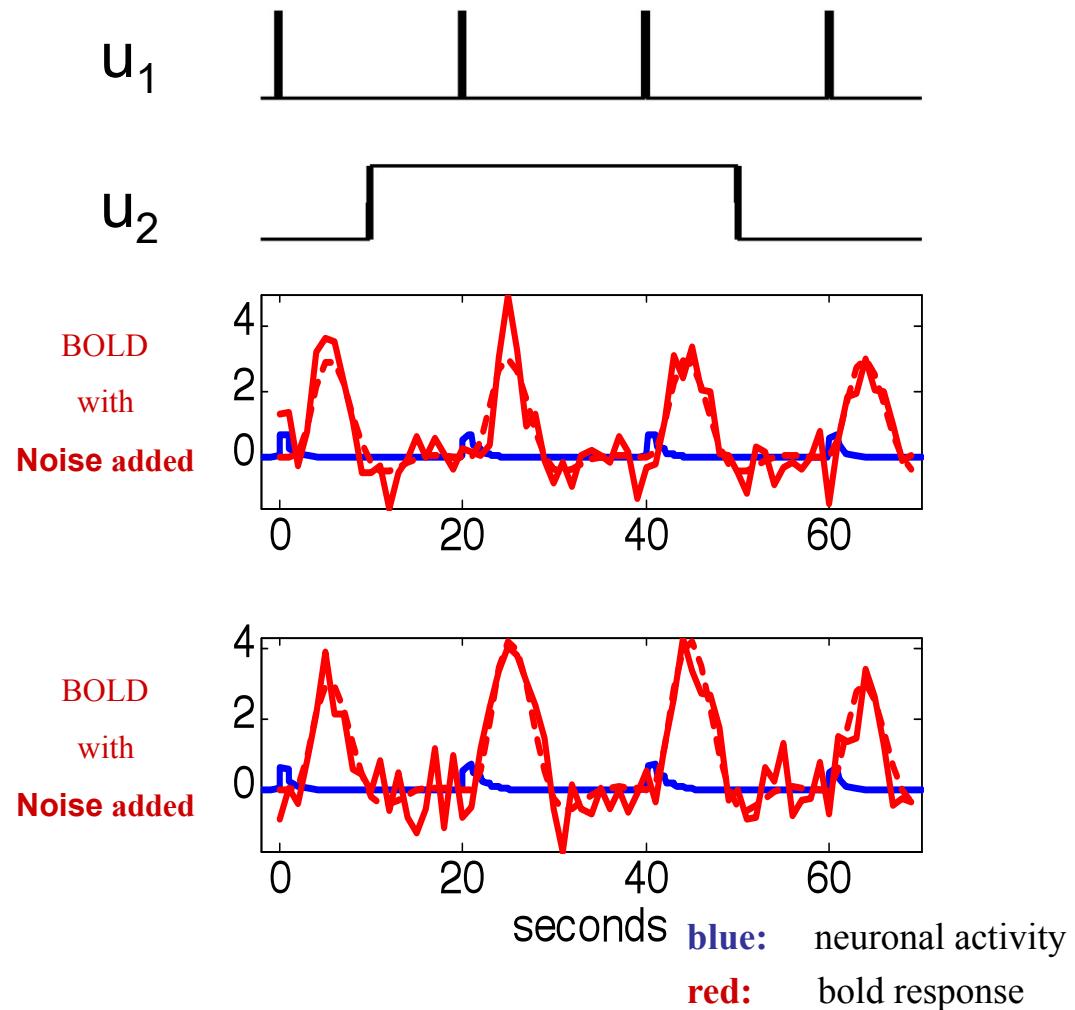
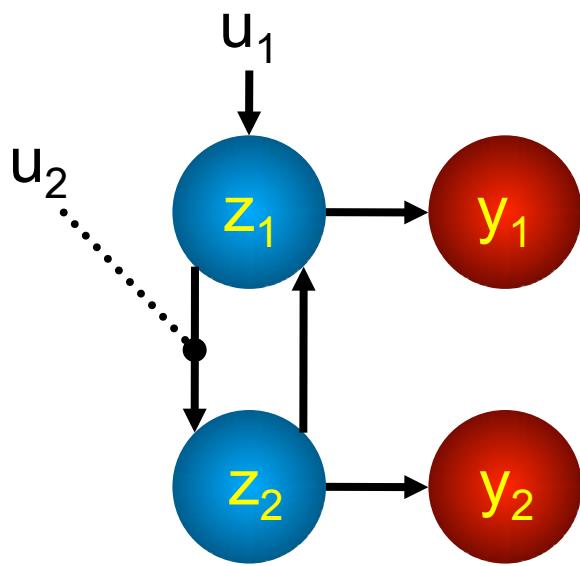
$$a_{12}, a_{21}, b_{21}^2 > 0$$

Hemodynamics: reciprocal connections



$h(u, \theta)$ represents the BOLD response (balloon model) to input

Hemodynamics: reciprocal connections



y represents simulated observation of BOLD response, i.e. includes noise
$$y = h(u, \theta) + e$$

Bilinear state equation in DCM for fMRI

state changes	connectivity	modulation of state connectivity	direct inputs	external inputs
\downarrow	\downarrow	\downarrow	\downarrow	\downarrow
$\begin{bmatrix} \dot{z}_1 \\ \vdots \\ \dot{z}_n \end{bmatrix} = \left\{ \begin{bmatrix} a_{11} & \cdots & a_{1n} \\ \vdots & \ddots & \vdots \\ a_{n1} & \cdots & a_{nn} \end{bmatrix} + \sum_{j=1}^m u_j \begin{bmatrix} b_{11}^j & \cdots & b_{1n}^j \\ \vdots & \ddots & \vdots \\ b_{n1}^j & \cdots & b_{nn}^j \end{bmatrix} \right\} \begin{bmatrix} z_1 \\ \vdots \\ z_n \end{bmatrix + \begin{bmatrix} c_{11} & \cdots & c_{1m} \\ \vdots & \ddots & \vdots \\ c_{n1} & \cdots & c_{nm} \end{bmatrix} \begin{bmatrix} u_1 \\ \vdots \\ u_m \end{bmatrix}$	n regions	m mod inputs	m drv inputs	

$$\dot{z} = (A + \sum_{j=1}^m u_j B^j)z + Cu$$

The hemodynamic model

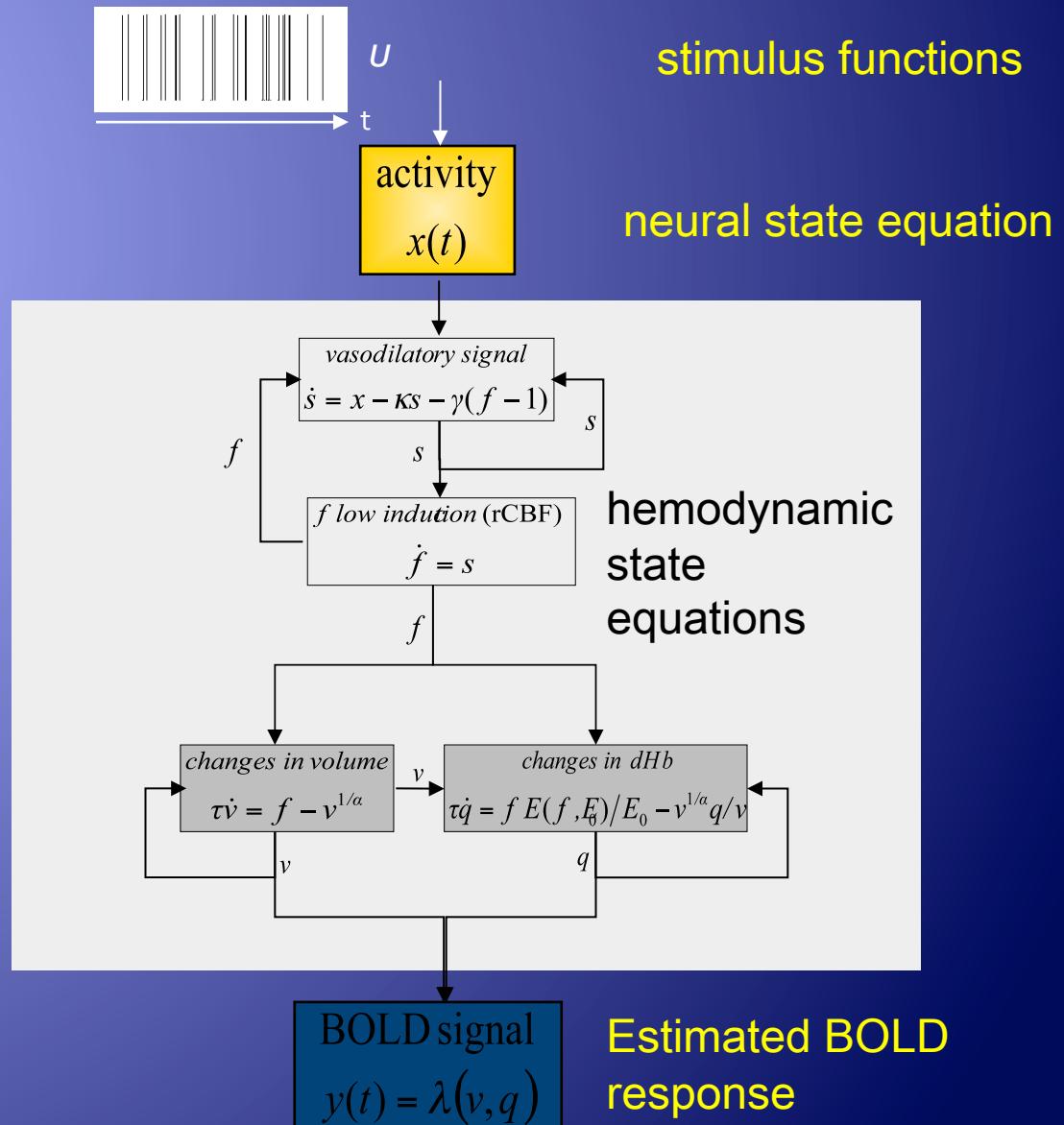
6 hemodynamic parameters:

$$\theta^h = \{K, \gamma, \tau, \alpha, \rho, \varepsilon\}$$

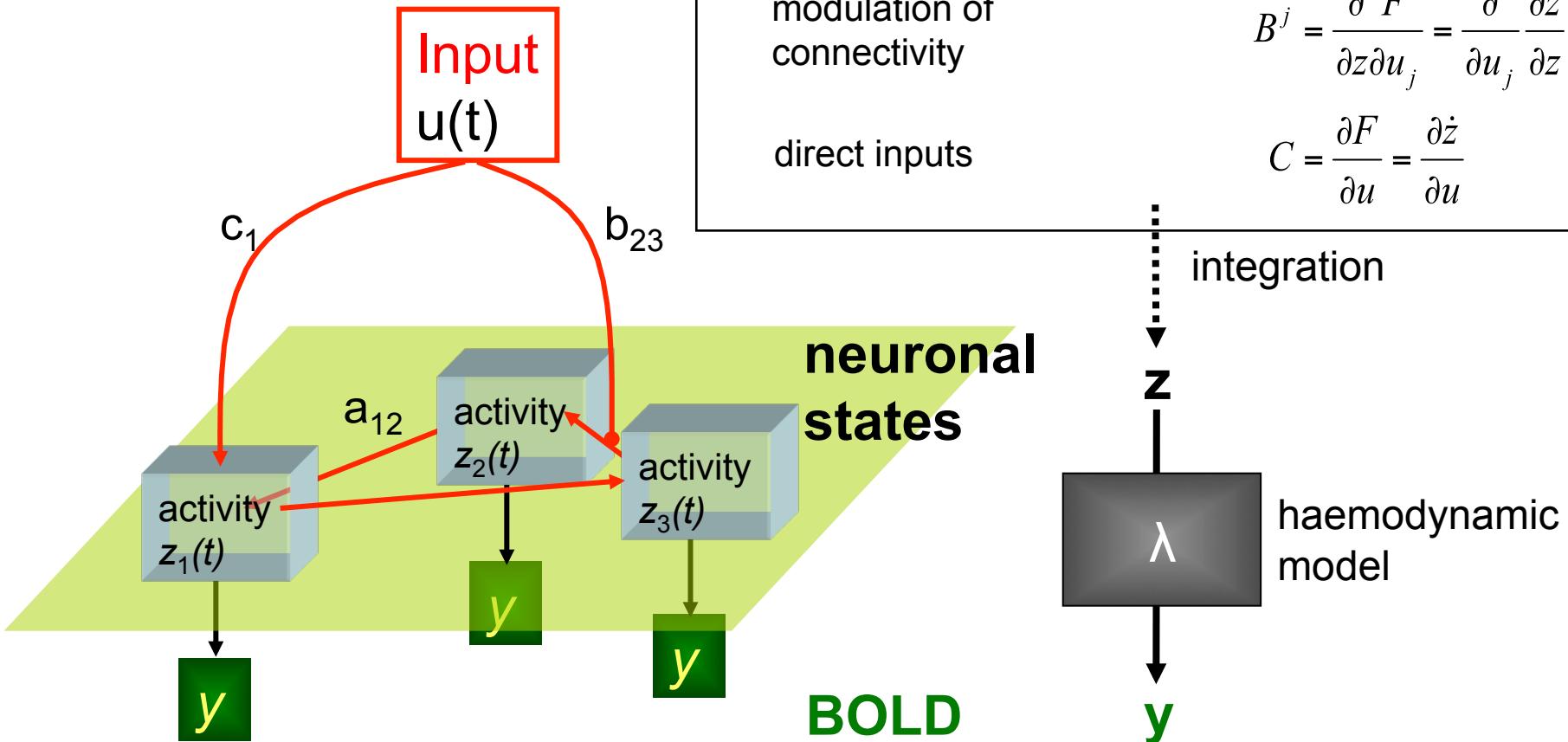


important for model fitting,
but of no interest for
statistical inference

Computed separately for
each area → region-
specific HRFs!



Conceptual overview



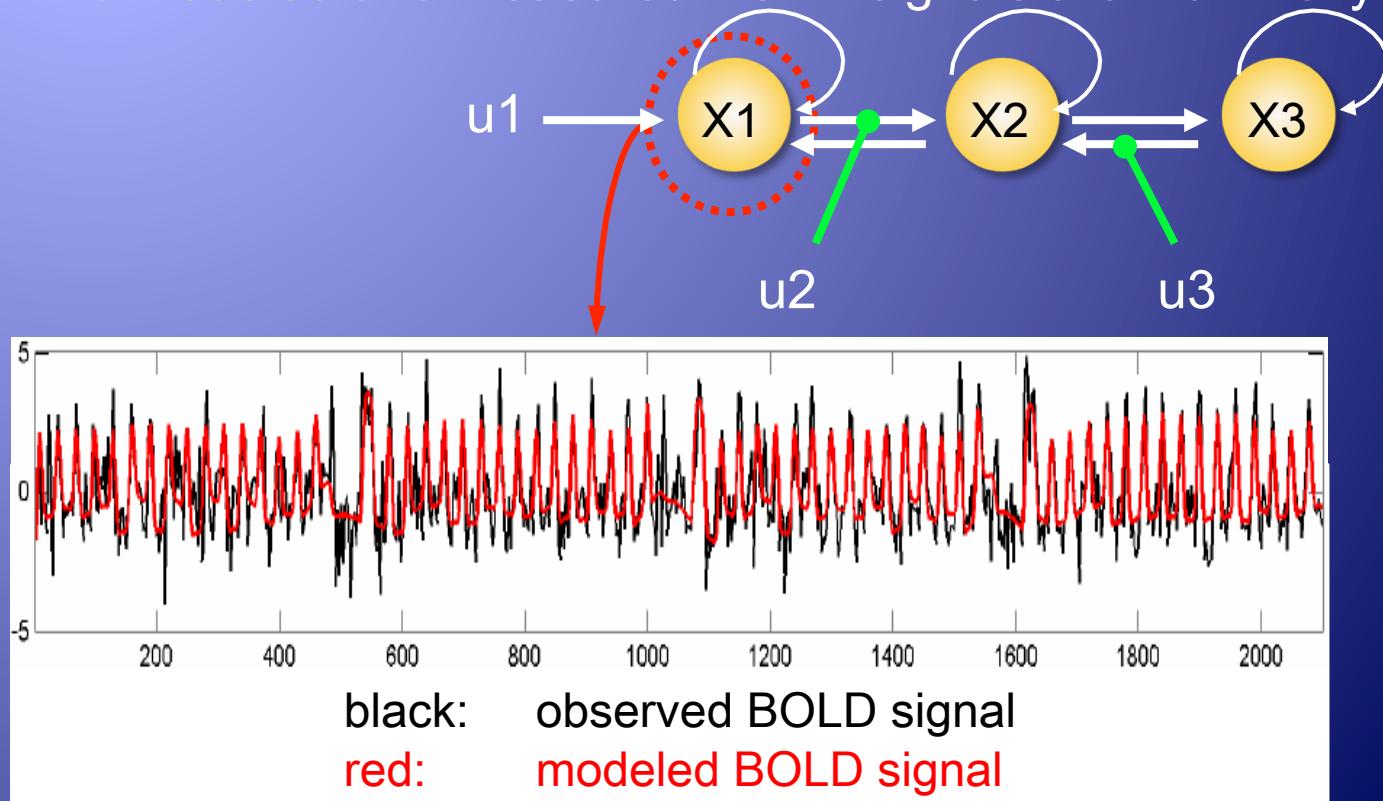
Measured vs Modeled BOLD signal

Recap

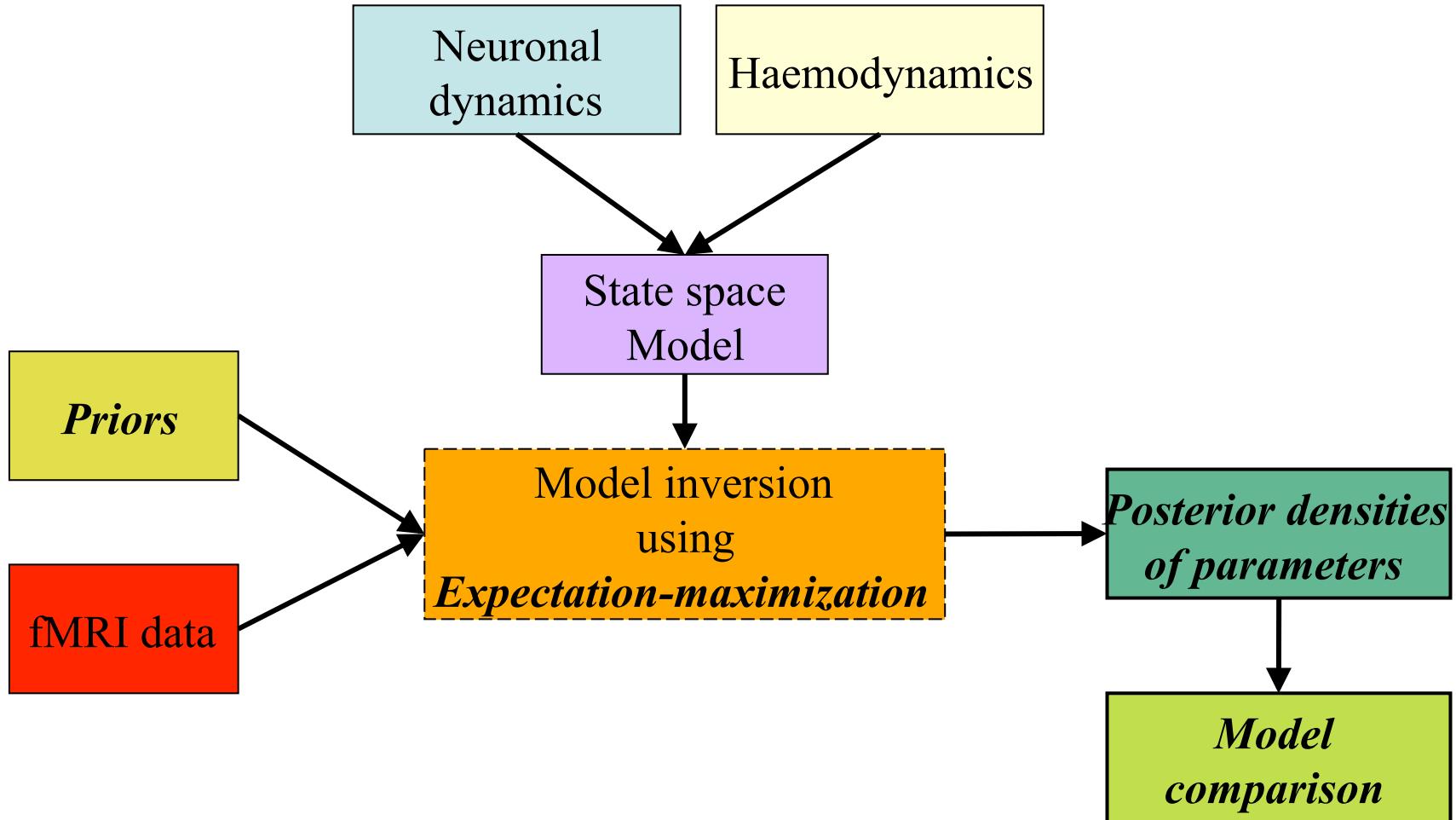
The aim of DCM is to estimate

- neural parameters {A, B, C}
- hemodynamic parameters

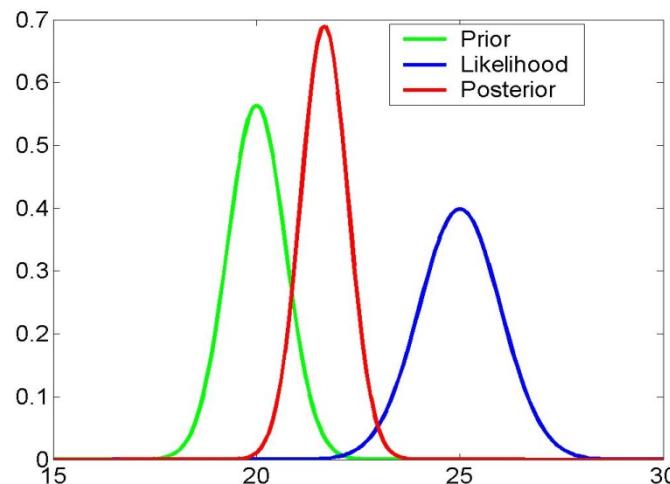
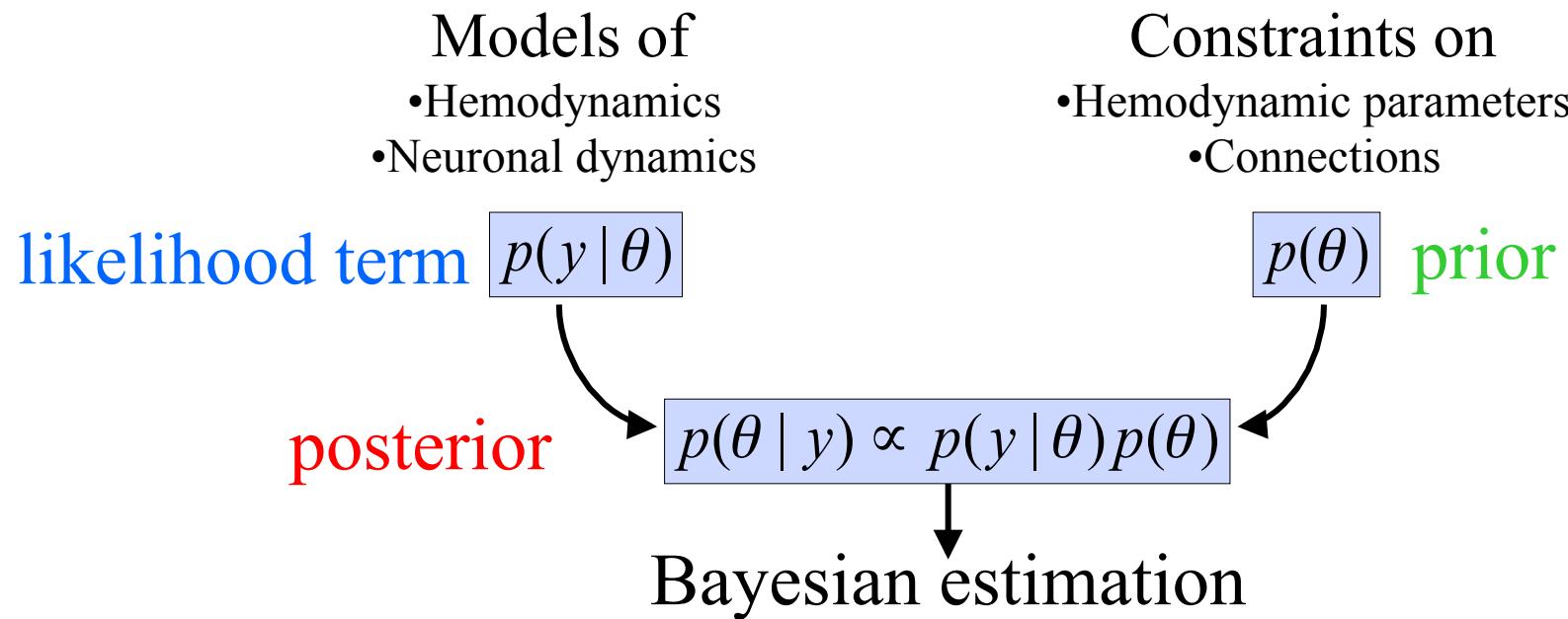
such that the **modeled** and measured BOLD signals are maximally similar.



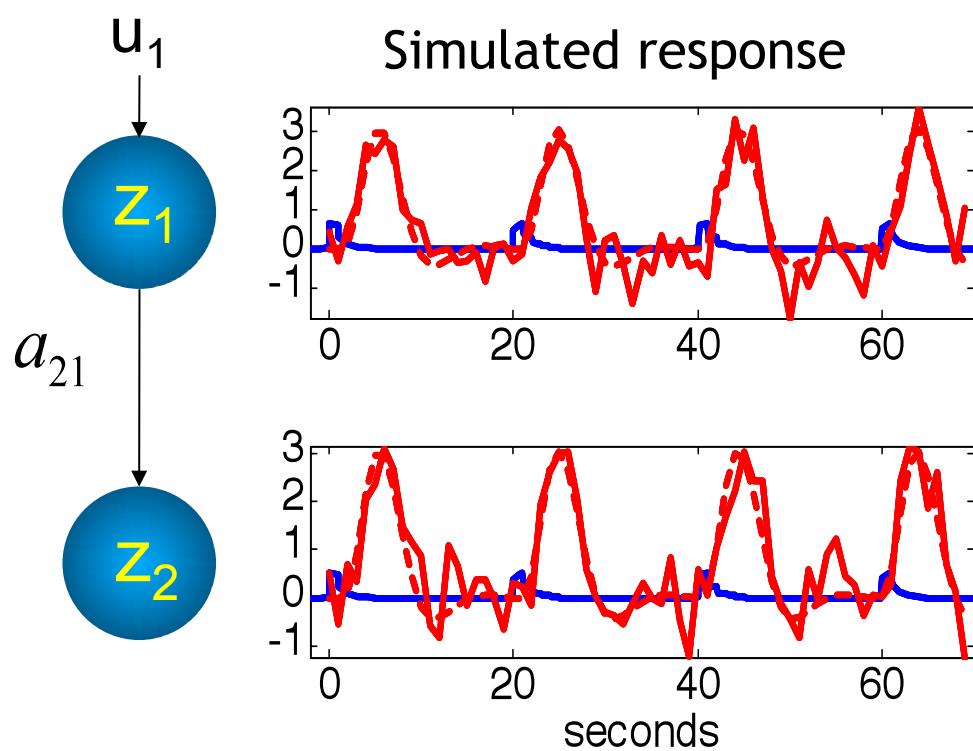
DCM roadmap



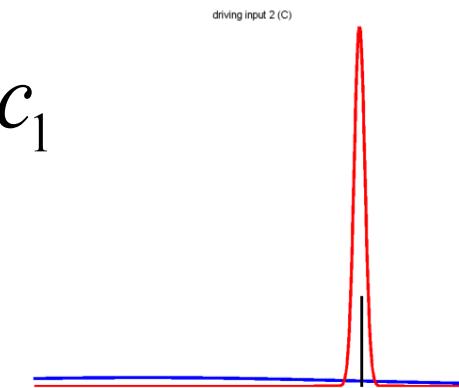
Estimation: Bayesian framework



Parameter estimation: an example

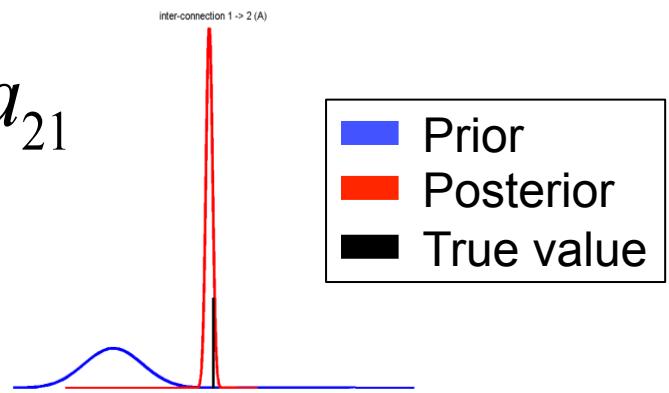


Input coupling, c_1



c_1

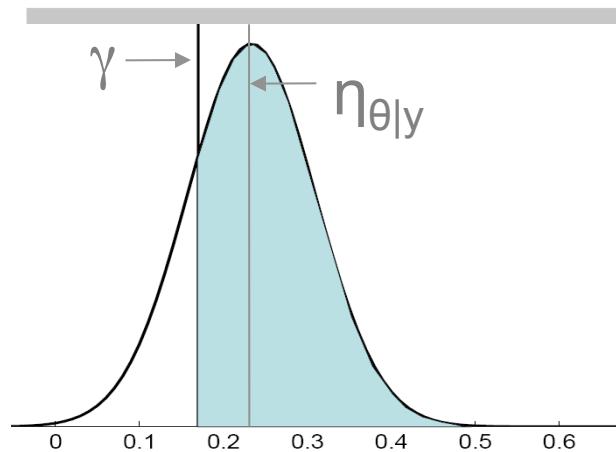
Forward coupling, a_{21}



a_{21}

Inference about DCM parameters: single-subject analysis

- Bayesian parameter estimation in DCM: Gaussian assumptions about the posterior distributions of the parameters
- Quantify the probability that a parameter (or contrast of parameters $c^T \eta_{\theta|y}$) is above a chosen threshold γ :



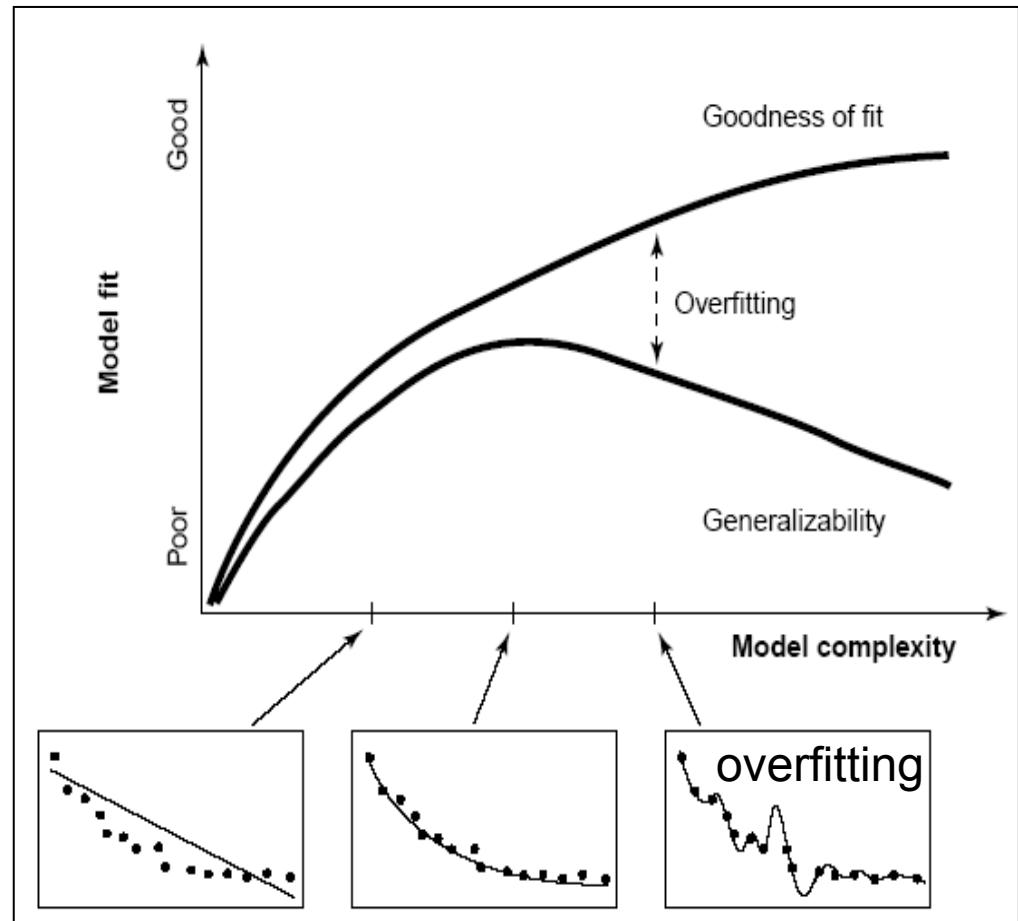
Model comparison and selection

Given competing hypotheses,
which model is the best?



$$\log p(y | m) = \text{accuracy}(m) - \text{complexity}(m)$$

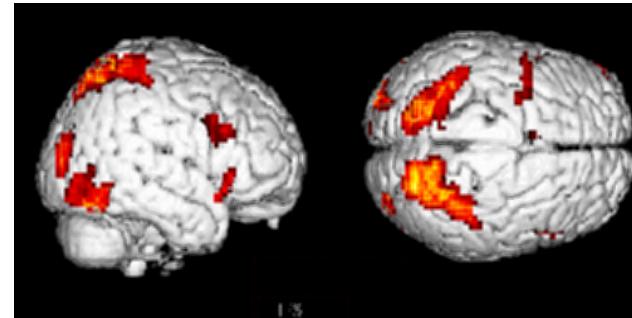
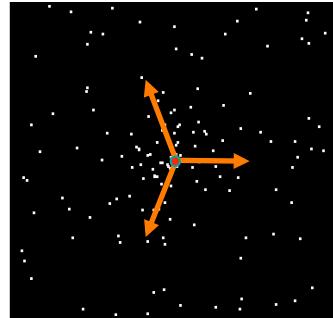
$$B_{ij} = \frac{p(y | m = i)}{p(y | m = j)}$$



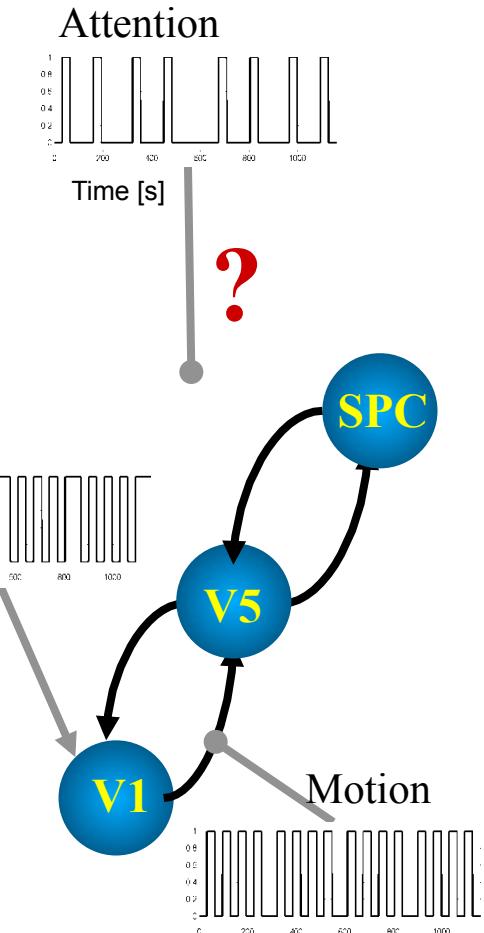
Pitt & Miyung (2002),
TICS

Attention to motion in the visual system

We used this model to assess the site of
attention modulation during *visual motion*
processing in an fMRI paradigm reported by
Büchel & Friston.



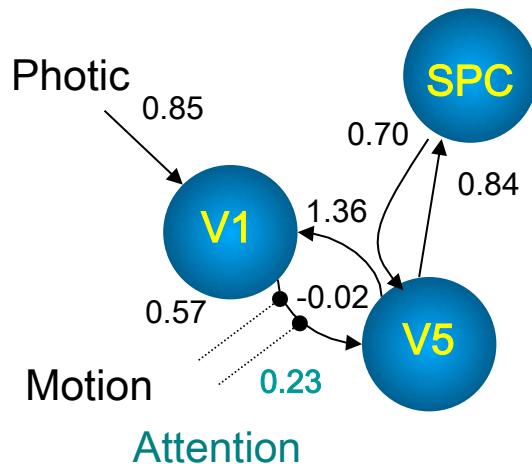
- fixation only
- observe static dots + photic → V1
- observe moving dots + motion → V5
- task on moving dots + attention → V5 + parietal cortex



Comparison of two simple models

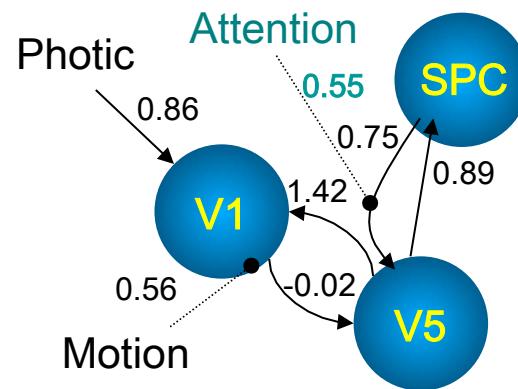
Model 1:

attentional modulation
of V1→V5



Model 2:

attentional modulation
of SPC→V5



Bayesian model selection: Model 1 better than model 2

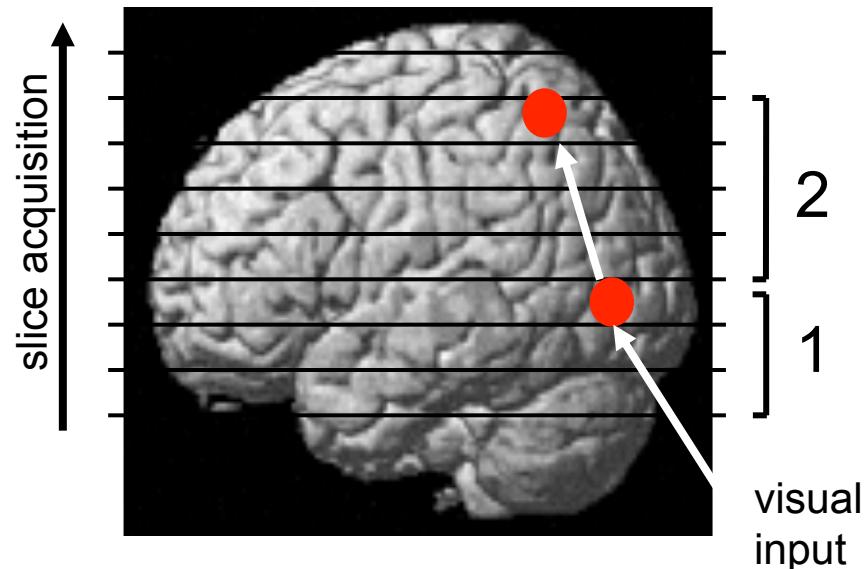
$$\log p(y | m_1) \gg \log p(y | m_2)$$

→ Decision for model 1: in this experiment, attention primarily modulates V1→V5

Extension I: Slice timing model

- potential timing problem in DCM:

temporal shift between regional time series because of multi-slice acquisition



- Solution:

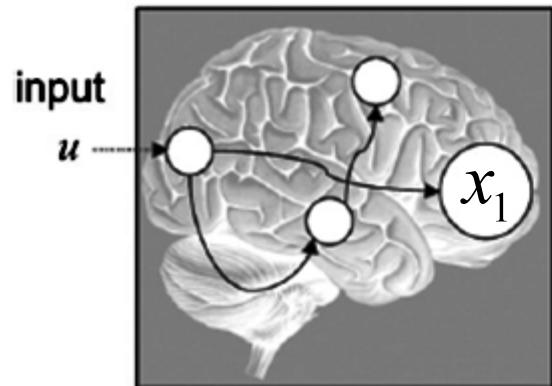
- Modeling of (known) slice timing of each area.

Slice timing extension now allows for any slice timing differences! (only works for sequential acquisitions)

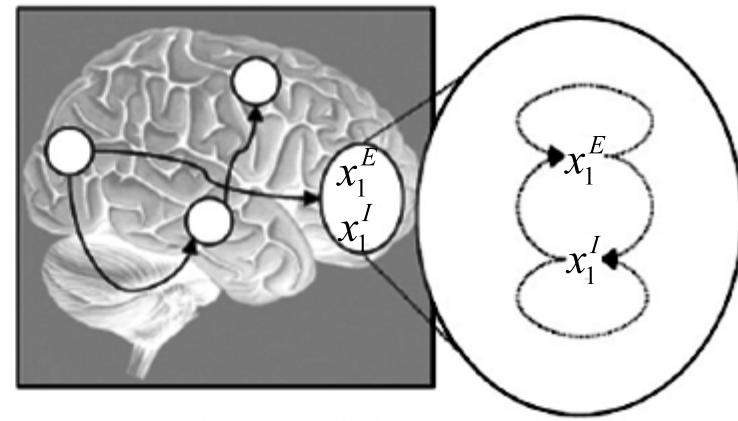
Long TRs (> 2 sec) no longer a limitation.

Extension II: Two-state model

Single-state DCM



Two-state DCM



$$\dot{x} = \mathfrak{I}x + Cu$$

$$\dot{x} = \mathfrak{I}x + Cu$$

$$\mathfrak{I}_y = A_{yy} + uB_{yy}$$

$$\mathfrak{I} = \begin{bmatrix} \mathfrak{I}_{11} & \dots & \mathfrak{I}_{1N} \\ \vdots & \ddots & \vdots \\ \mathfrak{I}_{N1} & \dots & \mathfrak{I}_{NN} \end{bmatrix} \quad x = \begin{bmatrix} x_1 \\ \vdots \\ x_N \end{bmatrix}$$

$$\mathfrak{I}_{ij}^{**} = \mu_{ij}^{**} \exp(A_{ij}^{**} + uB_{ij}^{**})$$

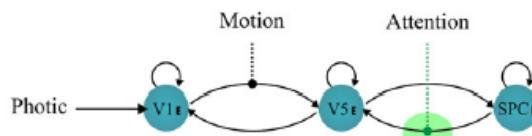
$$\mathfrak{I} = \begin{bmatrix} \mathfrak{I}_{11}^{EE} & \mathfrak{I}_{11}^{EI} & \dots & \mathfrak{I}_{1N}^{EE} & 0 \\ \mathfrak{I}_{11}^{IE} & \mathfrak{I}_{11}^{II} & & 0 & 0 \\ \vdots & & \ddots & \vdots & \\ \mathfrak{I}_{N1}^{EE} & 0 & & \mathfrak{I}_{NN}^{EE} & \mathfrak{I}_{NN}^{EI} \\ 0 & 0 & \dots & \mathfrak{I}_{NN}^{IE} & \mathfrak{I}_{NN}^{II} \end{bmatrix} \quad x = \begin{bmatrix} x_1^E \\ x_1^I \\ \vdots \\ x_N^E \\ x_N^I \end{bmatrix}$$

Extrinsic (between-region) coupling Intrinsic (within-region) coupling

1 vs. 2-state DCM of attention to motion

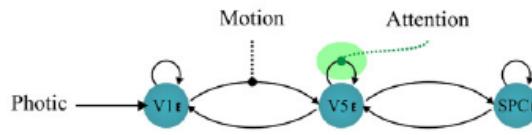
A)

Model 1



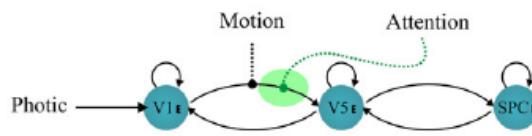
$$\begin{bmatrix} \mathfrak{I}_{V1V1}^{EE} & \mathfrak{I}_{V1V5}^{EE} & 0 \\ \mathfrak{I}_{V5V1}^{EE} & \mathfrak{I}_{V5V5}^{EE} & \mathfrak{I}_{V5SP}^{EE} \\ 0 & \mathfrak{I}_{SPV5}^{EE} & \mathfrak{I}_{SPSP}^{EE} \end{bmatrix}$$

Model 2



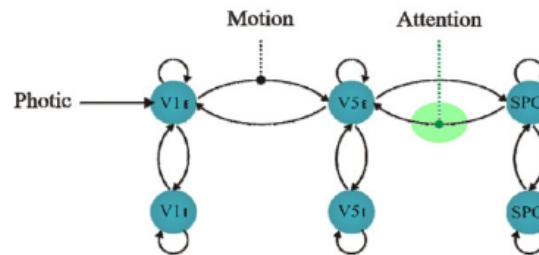
$$\begin{bmatrix} \mathfrak{I}_{V1V1}^{EE} & \mathfrak{I}_{V1V5}^{EE} & 0 \\ \mathfrak{I}_{V5V1}^{EE} & \mathfrak{I}_{V5V5}^{EE} & \mathfrak{I}_{V5SP}^{EE} \\ 0 & \mathfrak{I}_{SPV5}^{EE} & \mathfrak{I}_{SPSP}^{EE} \end{bmatrix}$$

Model 3



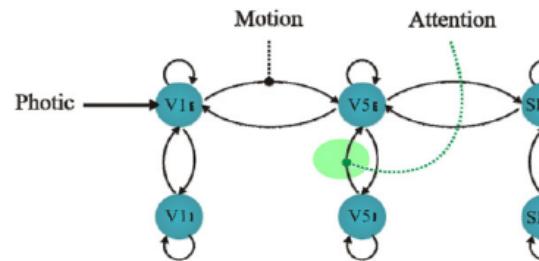
$$\begin{bmatrix} \mathfrak{I}_{V1V1}^{EE} & \mathfrak{I}_{V1V5}^{EE} & 0 \\ \mathfrak{I}_{V5V1}^{EE} & \mathfrak{I}_{V5V5}^{EE} & \mathfrak{I}_{V5SP}^{EE} \\ 0 & \mathfrak{I}_{SPV5}^{EE} & \mathfrak{I}_{SPSP}^{EE} \end{bmatrix}$$

**B) –Two-State DCM
Model 1**



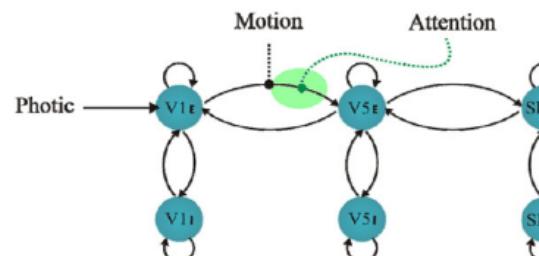
$$\begin{bmatrix} \mathfrak{I}_{V1V1}^{EE} & \mathfrak{I}_{V1V1}^{EI} & \mathfrak{I}_{V1V5}^{EE} & 0 & 0 & 0 \\ \mathfrak{I}_{V1V1}^{IE} & \mathfrak{I}_{V1V1}^{II} & 0 & 0 & 0 & 0 \\ \mathfrak{I}_{V5V1}^{EE} & 0 & \mathfrak{I}_{V5V5}^{EE} & \mathfrak{I}_{V5SP}^{EI} & \mathfrak{I}_{V5SP}^{EE} & 0 \\ 0 & 0 & \mathfrak{I}_{V5V5}^{IE} & \mathfrak{I}_{V5V5}^{II} & 0 & 0 \\ 0 & 0 & \mathfrak{I}_{SPV5}^{EE} & 0 & \mathfrak{I}_{SPSP}^{EE} & \mathfrak{I}_{SPSP}^{EI} \\ 0 & 0 & 0 & 0 & \mathfrak{I}_{SPSP}^{IE} & \mathfrak{I}_{SPSP}^{II} \end{bmatrix}$$

Model 2



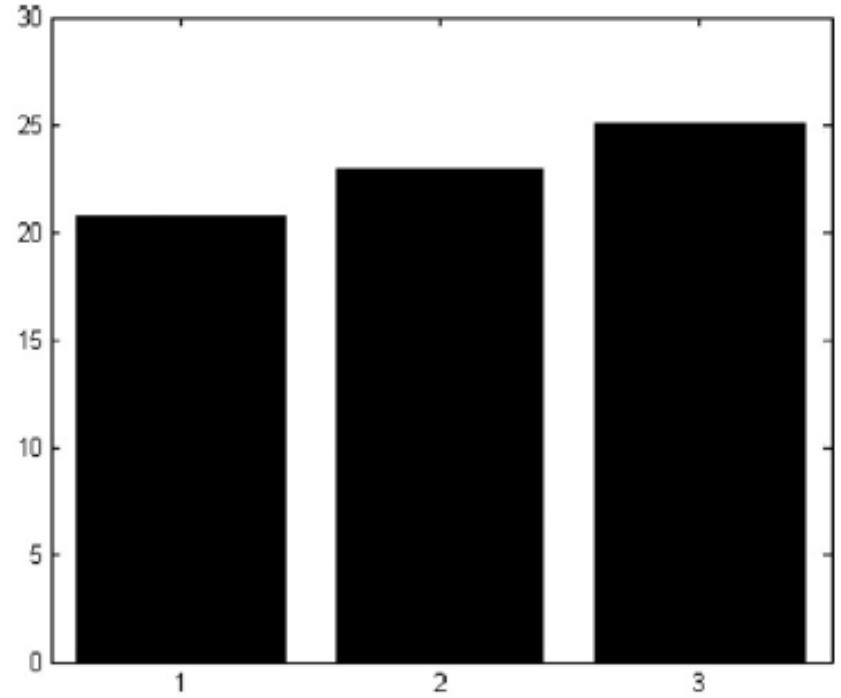
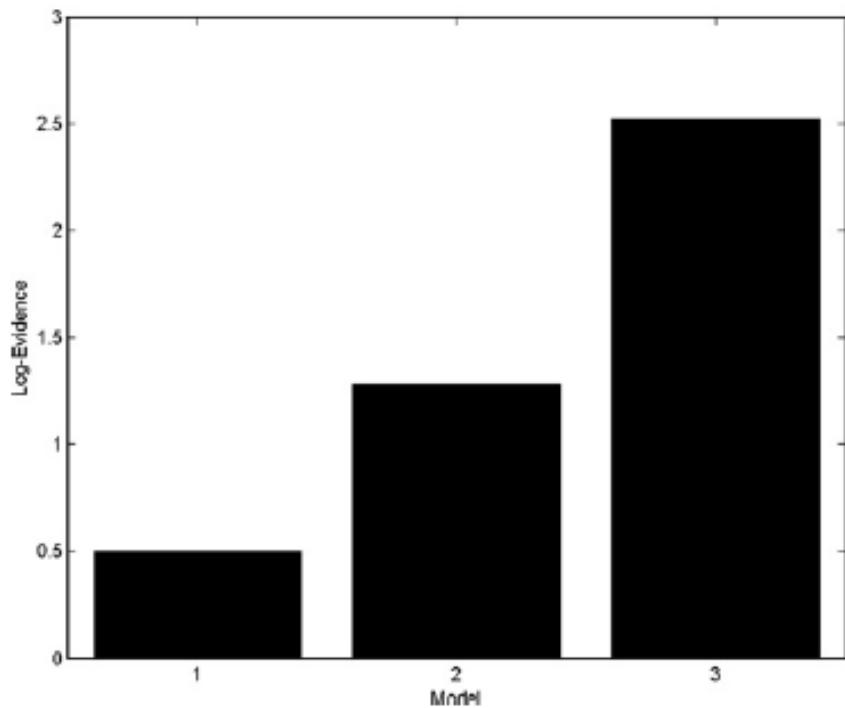
$$\begin{bmatrix} \mathfrak{I}_{V1V1}^{EE} & \mathfrak{I}_{V1V1}^{EI} & \mathfrak{I}_{V1V5}^{EE} & 0 & 0 & 0 \\ \mathfrak{I}_{V1V1}^{IE} & \mathfrak{I}_{V1V1}^{II} & 0 & 0 & 0 & 0 \\ \mathfrak{I}_{V5V1}^{EE} & 0 & \mathfrak{I}_{V5V5}^{EE} & \mathfrak{I}_{V5SP}^{EI} & \mathfrak{I}_{V5SP}^{EE} & 0 \\ 0 & 0 & \mathfrak{I}_{V5V5}^{IE} & \mathfrak{I}_{V5V5}^{II} & 0 & 0 \\ 0 & 0 & \mathfrak{I}_{SPV5}^{EE} & 0 & \mathfrak{I}_{SPSP}^{EE} & \mathfrak{I}_{SPSP}^{EI} \\ 0 & 0 & 0 & 0 & \mathfrak{I}_{SPSP}^{IE} & \mathfrak{I}_{SPSP}^{II} \end{bmatrix}$$

Model 3



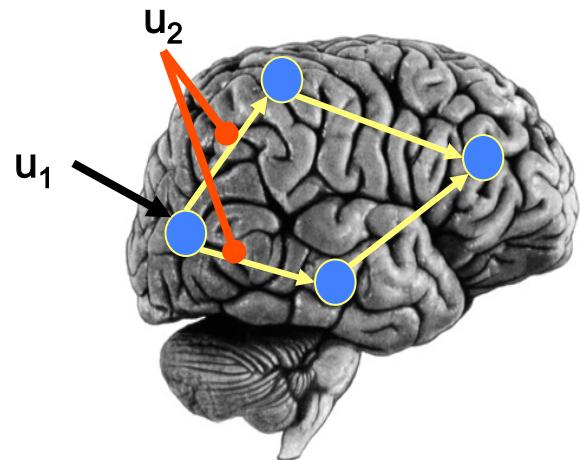
$$\begin{bmatrix} \mathfrak{I}_{V1V1}^{EE} & \mathfrak{I}_{V1V1}^{EI} & \mathfrak{I}_{V1V5}^{EE} & 0 & 0 & 0 \\ \mathfrak{I}_{V1V1}^{IE} & \mathfrak{I}_{V1V1}^{II} & 0 & 0 & 0 & 0 \\ \mathfrak{I}_{V5V1}^{EE} & 0 & \mathfrak{I}_{V5V5}^{EE} & \mathfrak{I}_{V5SP}^{EI} & \mathfrak{I}_{V5SP}^{EE} & 0 \\ 0 & 0 & \mathfrak{I}_{V5V5}^{IE} & \mathfrak{I}_{V5V5}^{II} & 0 & 0 \\ 0 & 0 & \mathfrak{I}_{SPV5}^{EE} & 0 & \mathfrak{I}_{SPSP}^{EE} & \mathfrak{I}_{SPSP}^{EI} \\ 0 & 0 & 0 & 0 & \mathfrak{I}_{SPSP}^{IE} & \mathfrak{I}_{SPSP}^{II} \end{bmatrix}$$

BMC: 1 vs. 2-state DCM of attention to motion



Extension III: Nonlinear DCM for fMRI

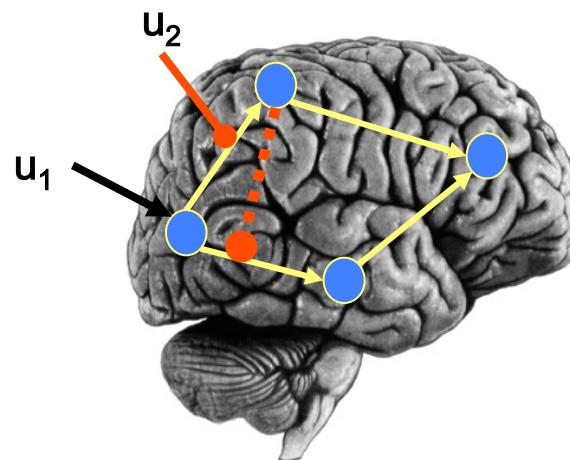
bilinear DCM



Bilinear state equation

$$\frac{dx}{dt} = \left(A + \sum_{i=1}^m u_i B^{(i)} \right) x + Cu$$

nonlinear DCM



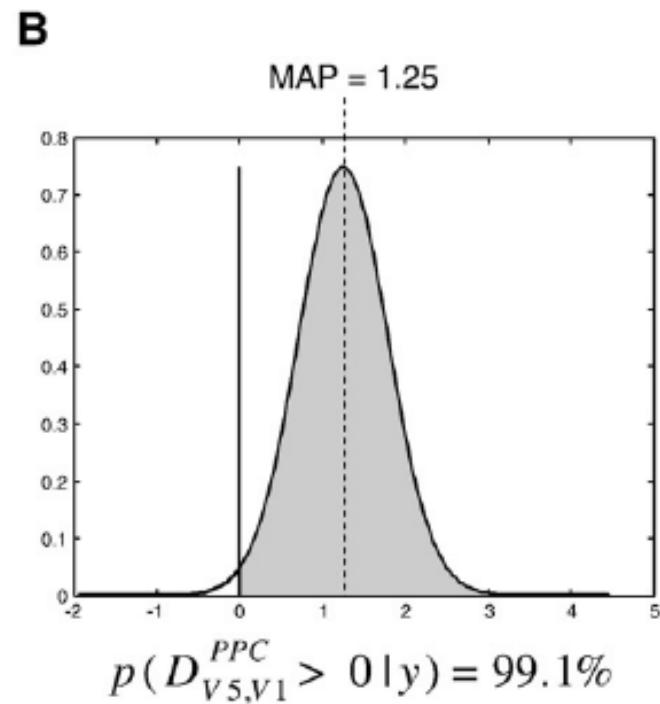
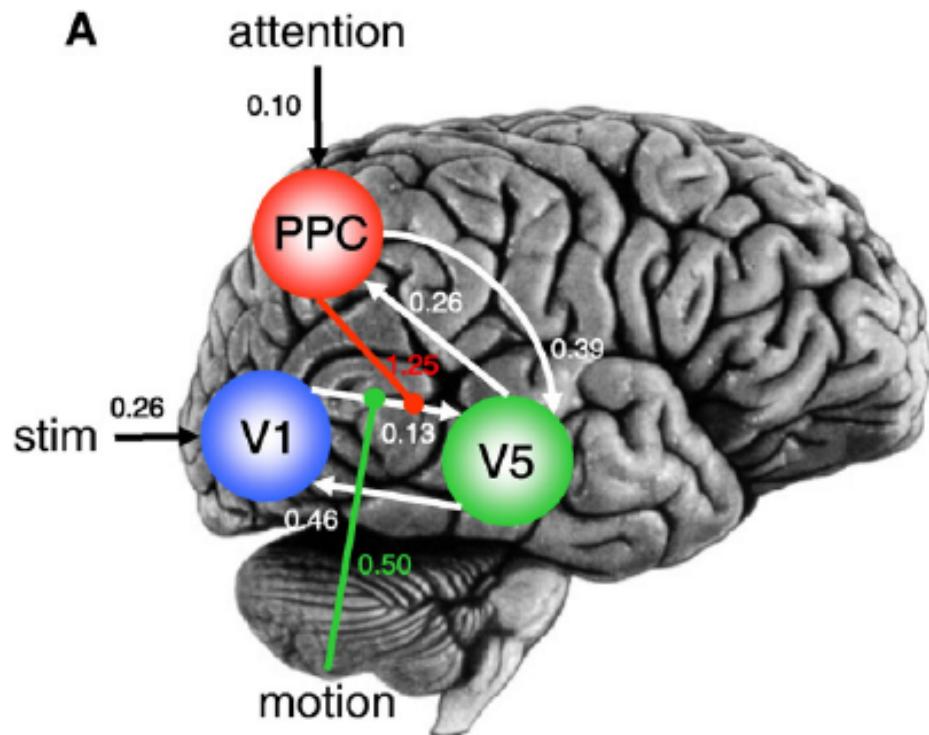
Nonlinear state equation

$$\frac{dx}{dt} = \left(A + \sum_{i=1}^m u_i B^{(i)} + \sum_{j=1}^n x_j D^{(j)} \right) x + Cu$$

DCM can model activity-dependent changes in connectivity;
connections can be enabled or gated by activity in one or more areas.

Extension III: Nonlinear DCM for fMRI

Can V5 activity during attention to motion be explained by allowing activity in SPC to modulate the V1-to-V5 connection?



Conclusions

Dynamic Causal Modeling (DCM) of fMRI is mechanistic model that is informed by anatomical and physiological principles.

DCM uses a deterministic differential equation to model neuro-dynamics (represented by matrices A,B and C)

DCM uses a Bayesian framework to estimate model parameters

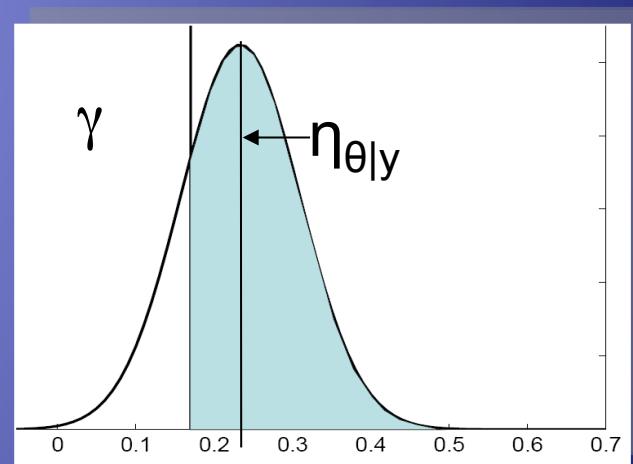
DCM provides an observation model for neuroimaging data, e.g. fMRI, M/EEG

DCM is not model or modality specific (Models will change and the method extended to other modalities e.g. ERPs)

Inference about DCM parameters:

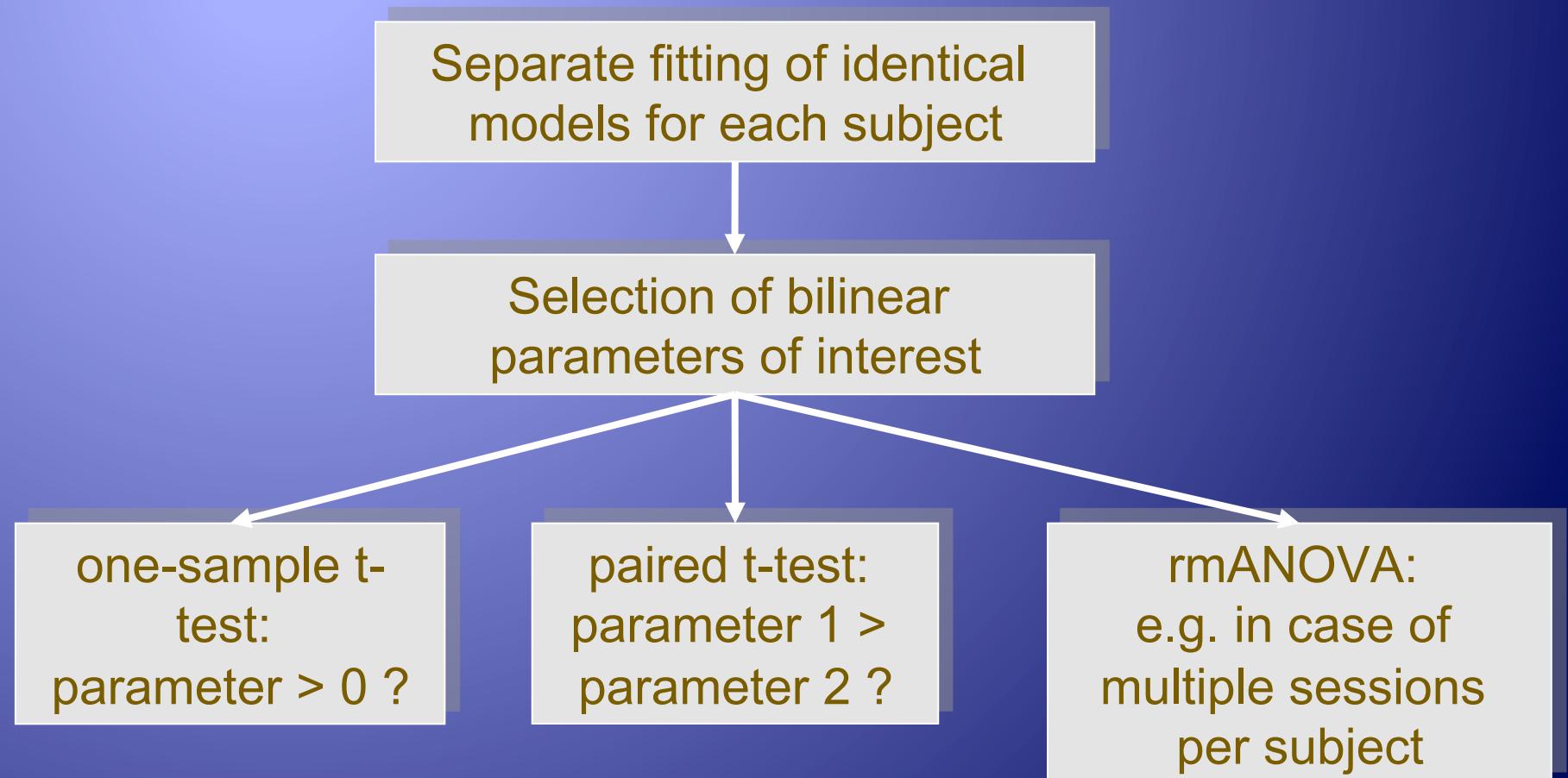
Bayesian single subject analysis

- The model parameters are distributions that have a mean $\eta_{\theta|y}$ and covariance $C_{\theta|y}$.
 - Use of the cumulative normal distribution to test the probability that a certain parameter is above a chosen threshold γ .
 - By default, γ is chosen as zero ("does the effect exist?").



Inference about DCM parameters: group analysis (classical)

- In analogy to “random effects” analyses in SPM, 2nd level analyses can be applied to DCM parameters:



GLM vs. DCM

- ◆ DCM tries to model the same phenomena as a GLM, just in a different way:
 - ◆ It is a model, based on connectivity and its modulation, for explaining experimentally controlled variance in local responses.
 - ◆ If there is no evidence for an experimental effect (no activation detected by a GLM) → inclusion of this region in a DCM is not meaningful.
 - ◆ Analysing an experiment using the GLM followed by DCM is not double dipping!

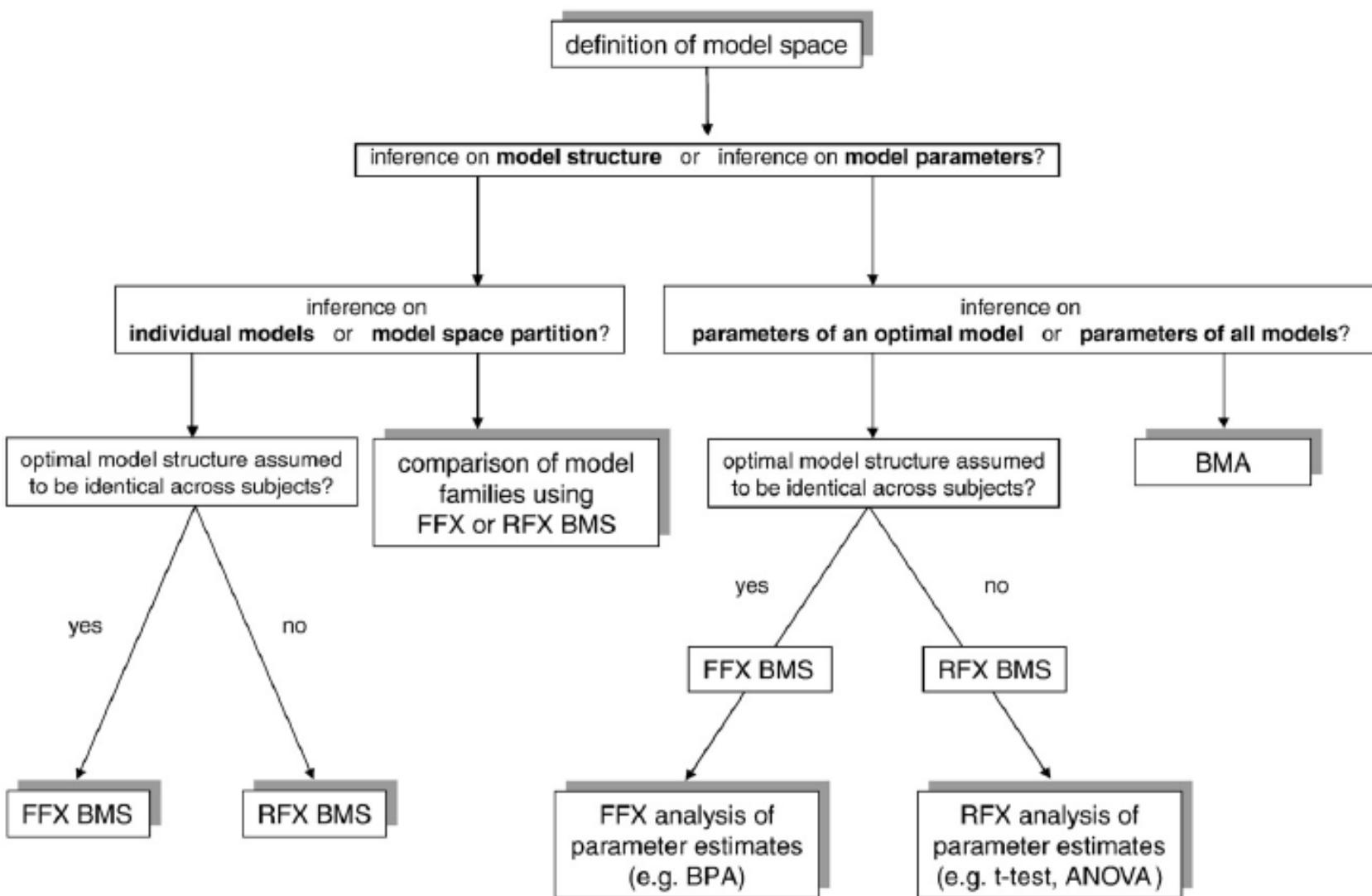
Planning a DCM-compatible study

- Suitable experimental design:
 - any design that is suitable for a GLM
 - preferably multi-factorial (e.g. 2 x 2)
 - e.g. one factor that varies the driving (sensory) input
 - and one factor that varies the contextual input
- Hypothesis and model:
 - Define specific *a priori* hypothesis
 - Which parameters are relevant to test this hypothesis?
 - If you want to verify that intended model is suitable to test this hypothesis, then use simulations
 - Define criteria for inference
 - What are the alternative models to test?

10 simple rules for DCM

1. Know what is causal about DCM.
 - ♦ The present state of one neuronal population causes dynamics in another via synaptic connections
 - ♦ External perturbations and/or neuronal activity can affect these interactions
 - ♦ Causality in DCM does not rely on temporal precedence.
2. Know your hypothesis and how to test it.
 - ♦ Tests of models vs. tests of parameters.
3. Use Bayesian model selection as a first step.
4. Motivate model space carefully.
 - ♦ E.g., permutations of a particular model or other data.

10 simple rules for DCM



10 simple rules for DCM

5. Choose an appropriate method for group-level inference on model structure
 - FFX – similar model across subjects
 - RFX – heterogeneous model across subjects
7. Know what you can and cannot do with Bayesian model selection.
 - E.g., can only compare models in fMRI with equivalent data.
9. Choose an appropriate method for group-level inference on parameters
10. Optimize experimental design and data acquisition
 - Factorial designs
 - Contiguous acquisition of slices vs. interleaved.
 - DCM for slice timing.

10 simple rules for DCM

9. Use anatomical information and computational models to refine DCMs
10. Report modeling approach and results in detail

The end