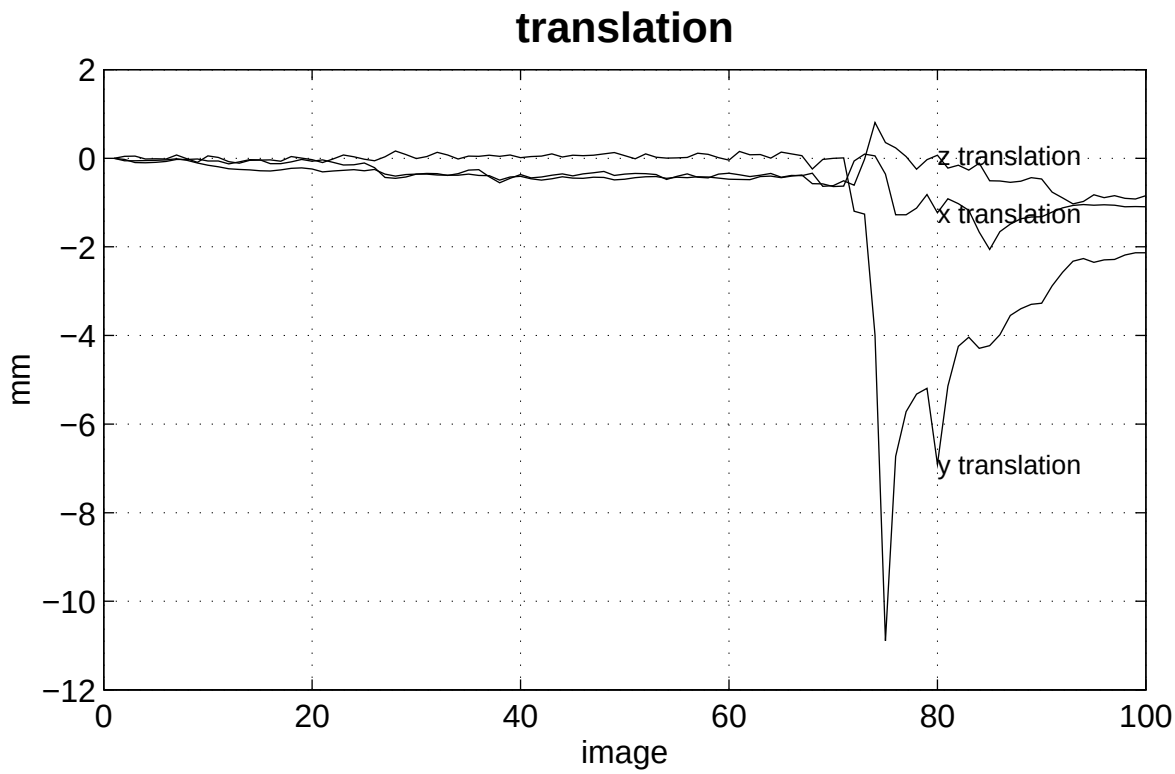
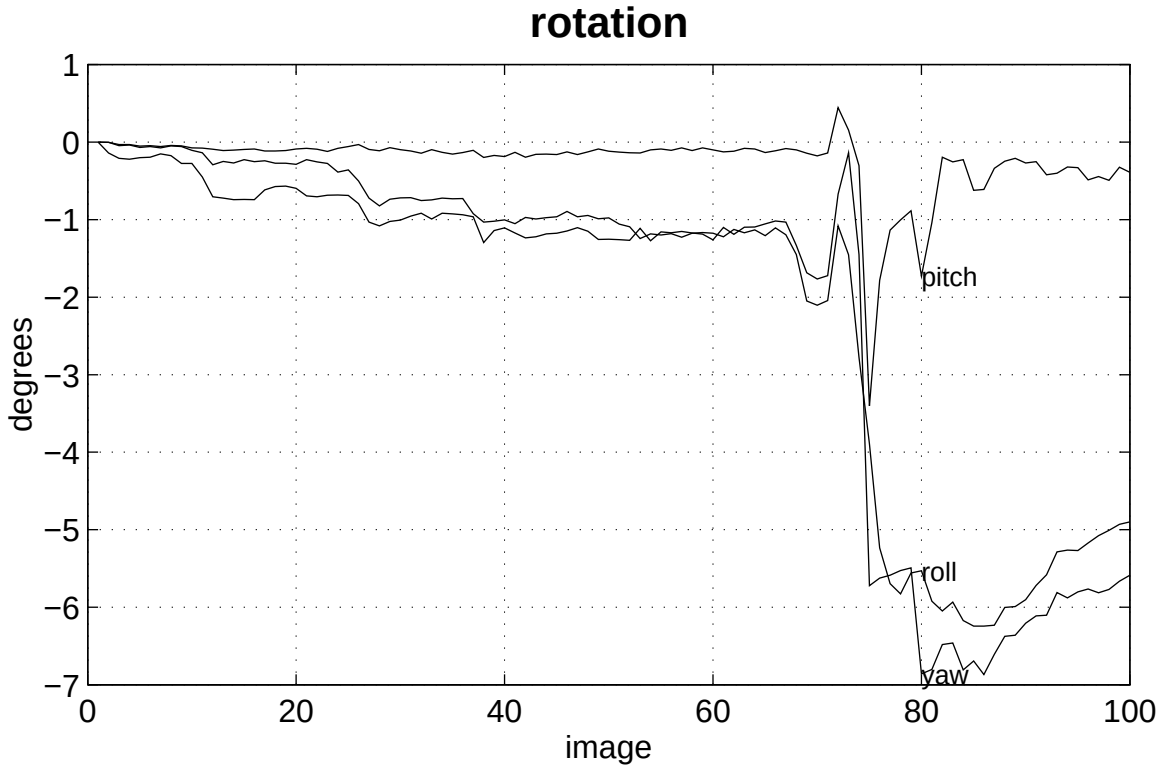

translation
2
0
−2
−4
−6
−8
−10
−12
mm
0
20
40
60
80
100
image
z translation
x translation
y translation


rotation
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0
−1
−2
−3
−4
−5
−6
−7
degrees
0
20
40
60
80
100
image
pitch
roll
yaw