

# Bayesian Inference for Linear Models

Bayesian Course  
Wellcome Trust Centre for Neuroimaging at UCL  
Feb 2013.

# Maximum Likelihood

## Maximum Likelihood

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### Bayesian Linear Models

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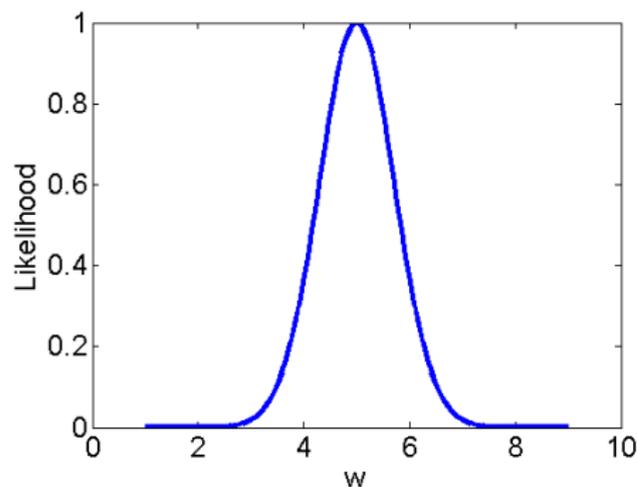
### Augmented Form

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### References

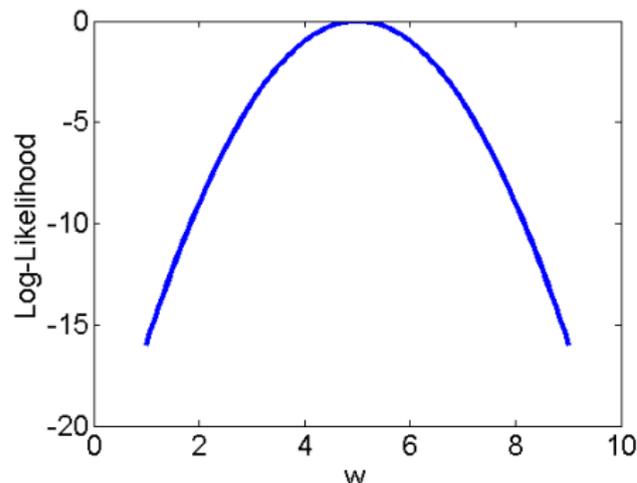
Set parameter(s)  $w$  to maximise the likelihood,  $p(y|w)$ .



# Maximum Likelihood

Set parameter(s)  $w$  to maximise the log-likelihood

$$L = \log p(y|w)$$



The gradient  $dL/dw = 0$  at the maximum.

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# General Linear Model

The General Linear Model (GLM) is given by

$$y = Xw + e$$

where  $y$  are data,  $X$  is a design matrix, and  $e$  are zero mean Gaussian errors with covariance  $V$ . The above equation implicitly defines the likelihood function

$$p(y|w) = N(y; Xw, V)$$

where the Normal density is given by

$$N(x; \mu, V) = \frac{1}{(2\pi)^{N/2} |V|^{1/2}} \exp\left(-\frac{1}{2}(x - \mu)^T V^{-1}(x - \mu)\right)$$

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# Maximum Likelihood

If we know  $V$  then we can estimate  $w$  by maximising the likelihood or equivalently the log-likelihood

$$L = -\frac{N}{2} \log 2\pi - \frac{1}{2} \log |V| - \frac{1}{2} (y - Xw)^T V^{-1} (y - Xw)$$

We can compute the gradient with help from the Matrix Reference Manual or Wikipedia's Matrix Calculus page:

$$\frac{dx^T A}{dx} = A, \quad \frac{dAx}{dx} = A^T$$

and

$$\frac{dx^T Ax}{dx} = Ax + A^T x = 2Ax$$

if  $A$  is symmetric.

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# Maximum Likelihood

If we know  $V$  then we can estimate  $w$  by maximising the likelihood or equivalently the log-likelihood

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We can compute the gradient with help from the Matrix Reference Manual or Wikipedia's Matrix Calculus page:

$$\frac{dL}{dw} = X^T V^{-1} y - X^T V^{-1} Xw$$

and set it to zero. This leads to the 'normal equations' and the solution

$$\hat{w}_{ML} = (X^T V^{-1} X)^{-1} X^T V^{-1} y$$

This is often referred to as Weighted Least Squares (WLS),  $\hat{w}_{ML} = \hat{w}_{WLS}$ .

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# fMRI analysis

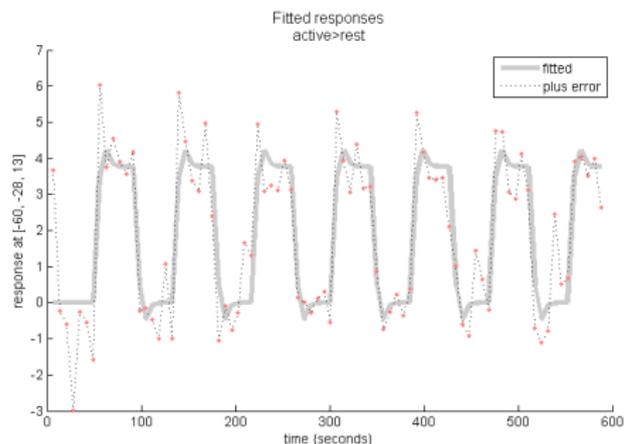
For fMRI time series analysis we have a linear model at each voxel  $i$

$$y_i = Xw_i + e_i$$

$V_i = \text{Cov}(e_i)$  is estimated first (see later) and then the regression coefficients are computed using Maximum Likelihood (ML) estimation.

$$\hat{w}_i = (X^T V_i^{-1} X)^{-1} X^T V_i^{-1} y_i$$

The fitted responses are then  $\hat{y}_i = X\hat{w}_i$  (SPM Manual)



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The uncertainty in the ML estimates is given by

$$S = (X^T V_i^{-1} X)^{-1}$$

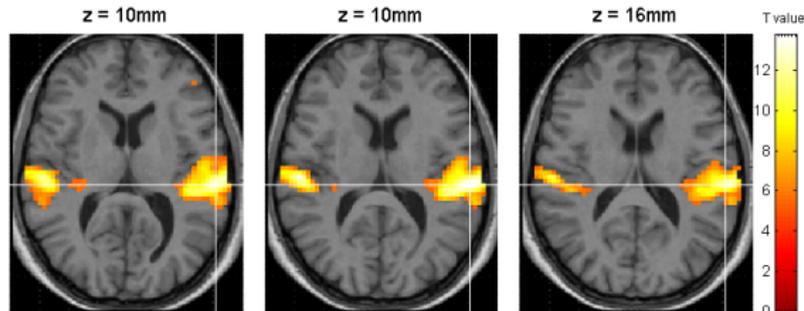
Contrast vectors  $c$  can then be used to test for specific effects

$$\mu_c = c^T \hat{W}_i$$

The uncertainty in the effect is then

$$\sigma_c^2 = c^T S c$$

and a t-score is then given by  $t = \mu_c / \sigma_c$



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For isotropic error covariance  $V = \lambda I$ , the normal equations are

$$\frac{dL}{dw} = \lambda X^T y - \lambda X^T X w$$

This leads to the Ordinary Least Squares (OLS) solution

$$\hat{w}_{ML} = \hat{w}_{OLS},$$

$$\hat{w}_{OLS} = (X^T X)^{-1} X^T y$$

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A Bayesian GLM is defined as

$$\begin{aligned}y &= Xw + e_1 \\ w &= \mu_w + e_2\end{aligned}$$

where the errors are zero mean Gaussian with covariances  $\text{Cov}[e_1] = C_y$  and  $\text{Cov}[e_2] = C_w$ .

$$\begin{aligned}p(y|w) &\propto \exp\left(-\frac{1}{2}(y - Xw)^T C_y^{-1}(y - Xw)\right) \\ p(w) &\propto \exp\left(-\frac{1}{2}(w - \mu_w)^T C_w^{-1}(w - \mu_w)\right)\end{aligned}$$

The posterior distribution is then

$$p(w|y) \propto p(y|w)p(w)$$

Taking logs and keeping only those terms that depend on  $w$  gives

$$\begin{aligned}\log p(w|y) &= -\frac{1}{2}(y - Xw)^T C_y^{-1}(y - Xw) \\ &\quad - \frac{1}{2}(w - \mu_w)^T C_w^{-1}(w - \mu_w) + \dots \\ &= -\frac{1}{2}w^T (X^T C_y^{-1} X + C_w^{-1}) w \\ &\quad + w^T (X^T C_y^{-1} y + C_w^{-1} \mu_w) + \dots\end{aligned}$$

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# Bayesian GLM

If  $p(x) = N(x; m, S)$  then

$$p(x) \propto \exp\left(-\frac{1}{2}(x - m)^T S^{-1}(x - m)\right)$$

Taking logs of the Gaussian density  $p(x)$  and keeping only those terms that depend on  $x$  gives

$$\log p(x) = -\frac{1}{2}x^T S^{-1}x + x^T S^{-1}m + ..$$

For our posterior we have

$$\begin{aligned}\log p(w|y) &= -\frac{1}{2}w^T(X^T C_y^{-1}X + C_w^{-1})w \\ &+ w^T(X^T C_y^{-1}y + C_w^{-1}\mu_w) + ..\end{aligned}$$

Equating terms gives

$$\begin{aligned}p(w|y) &= N(w; m_w, S_w) \\ S_w^{-1} &= X^T C_y^{-1}X + C_w^{-1} \\ m_w &= S_w(X^T C_y^{-1}y + C_w^{-1}\mu_w)\end{aligned}$$

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The posterior density is

$$\begin{aligned}p(w|y) &= N(w; m_w, S_w) \\ S_w^{-1} &= X^T C_y^{-1} X + C_w^{-1} \\ m_w &= S_w (X^T C_y^{-1} y + C_w^{-1} \mu_w)\end{aligned}$$

The posterior precision is the sum of the prior precision and the data precision.

The posterior mean is a relative precision weighted combination of the data mean and the prior mean.

If  $\mu_w = 0$  we have a *shrinkage prior*.

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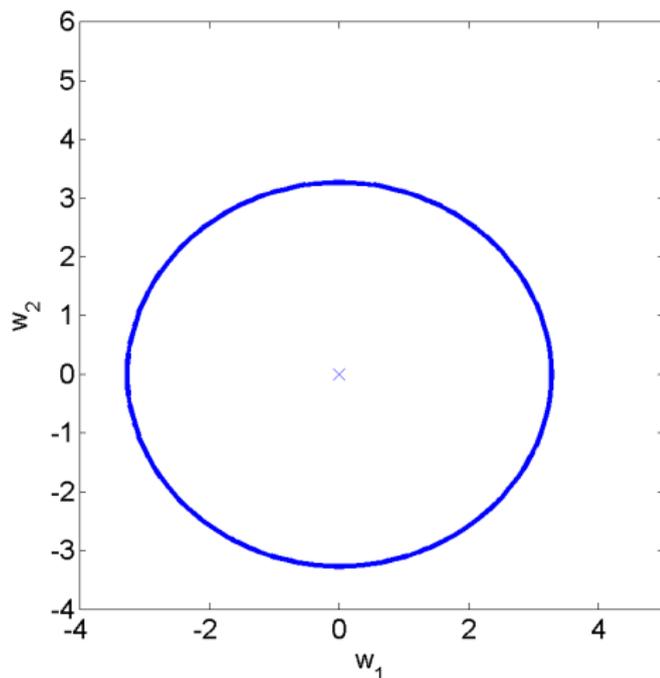
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# Bayesian GLM with two parameters

The prior has mean  $\mu_w = [0, 0]^T$  (cross) and precision  $C_w^{-1} = \text{diag}([1, 1])$ .



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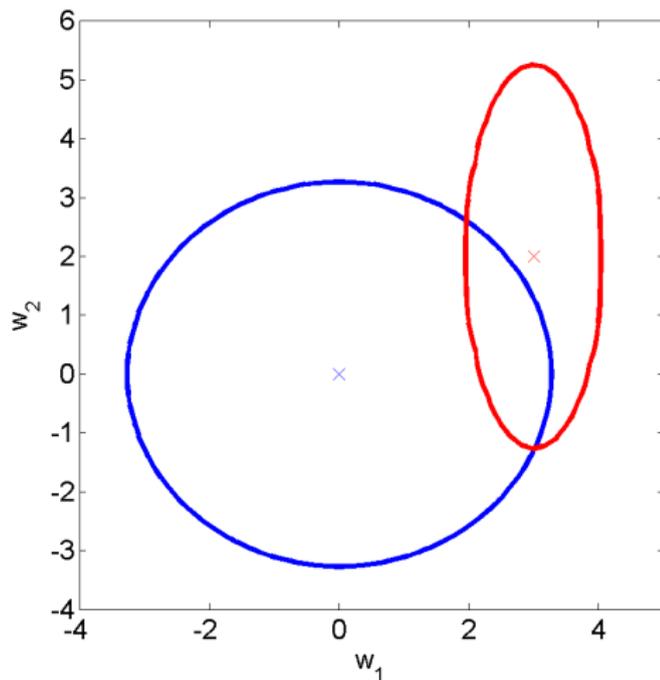
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# Bayesian GLM with two parameters

The likelihood has mean  $X^T y = [3, 2]^T$  (circle) and precision  $(X^T C_y^{-1} X)^{-1} = \text{diag}([10, 1])$ .



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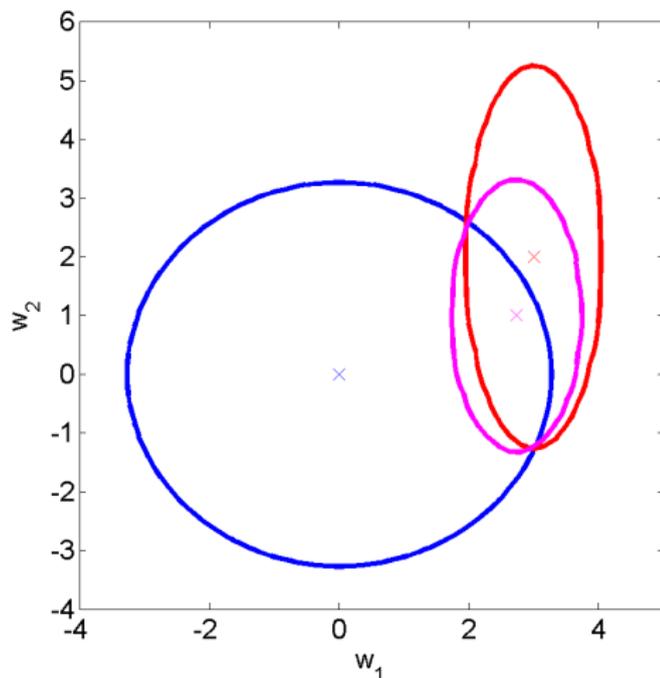
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# Bayesian GLM with two parameters

The posterior has mean  $m = [2.73, 1]^T$  (cross) and precision  $S_w^{-1} = \text{diag}([11, 2])$ .



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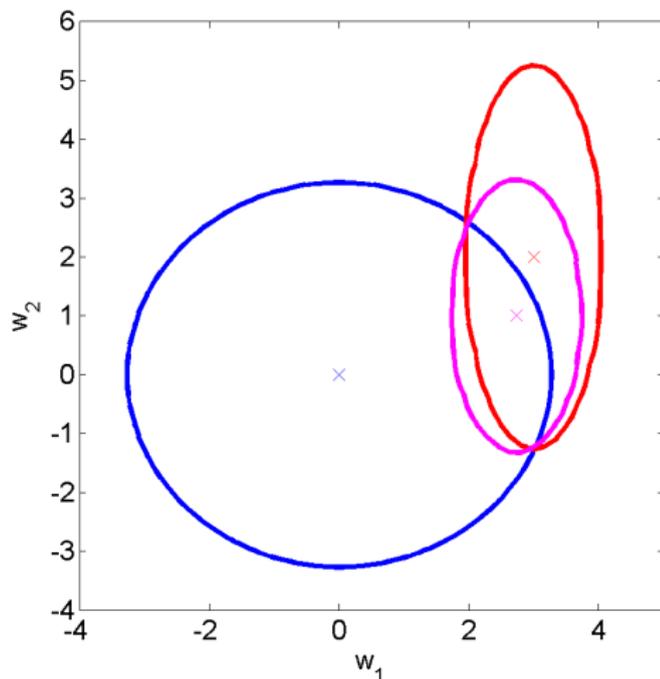
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# Bayesian GLM with two parameters

In this example, the measurements are more informative about  $w_1$  than  $w_2$ . This is reflected in the posterior distribution.



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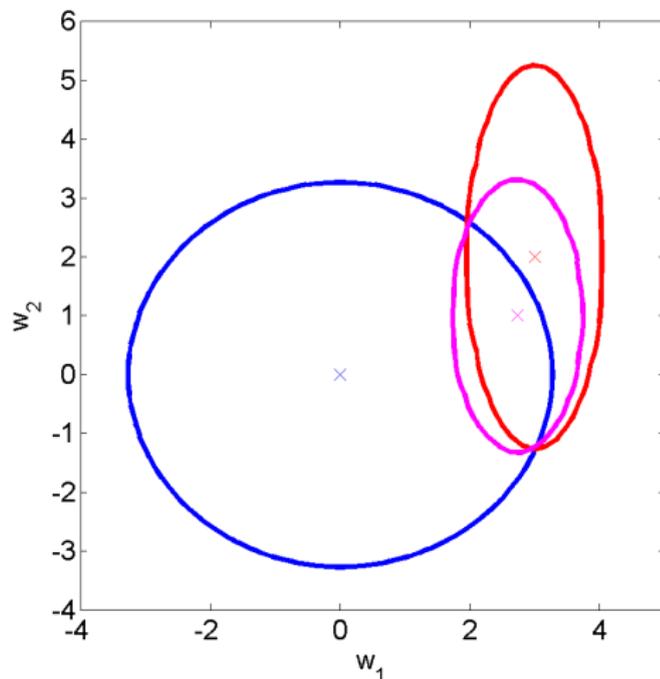
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# Shrinkage Prior

If  $\mu_w = 0$  we have a *shrinkage prior*.



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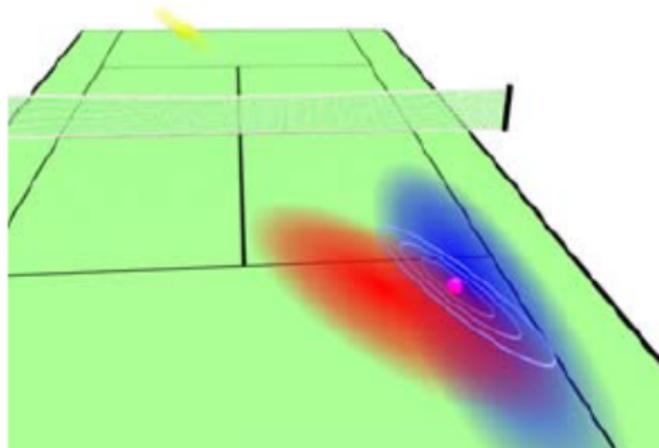
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# Tennis

From Wolpert and Ghahramani (2006)



$$\begin{aligned}p(w|y) &= N(w; m_w, S_w) \\S_w^{-1} &= X^T C_y^{-1} X + C_w^{-1} \\m_w &= S_w(X^T C_y^{-1} y + C_w^{-1} \mu_w)\end{aligned}$$

Given a contrast,  $C$ , testing for effect  $s = C^T w$  the posterior distribution of the effect is

$$p(s|Y) = N(s; m_s, C_s)$$

where

$$m_s = C^T m_w$$

and

$$C_s = C^T S_w C$$

For example  $C^T = [1 \ -1]$  to look for difference between two conditions.

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# fMRI example - Effect Size

Define an effect size threshold,  $s_t$

Define the following classifications

Positively Activated

$$p_{posact} = p(\mathbf{s} > \mathbf{s}_t | \mathbf{y})$$

Negatively Activated

$$p_{negact} = p(\mathbf{s} < -\mathbf{s}_t | \mathbf{y})$$

Not Activated

$$p_{notact} = p(-\mathbf{s}_t \leq \mathbf{s} \leq \mathbf{s}_t | \mathbf{y})$$

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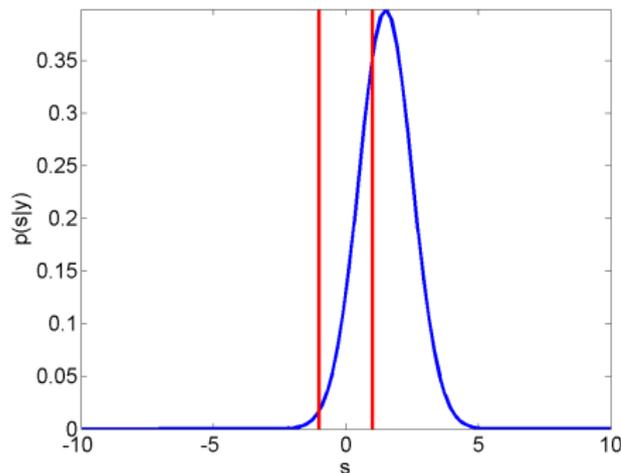
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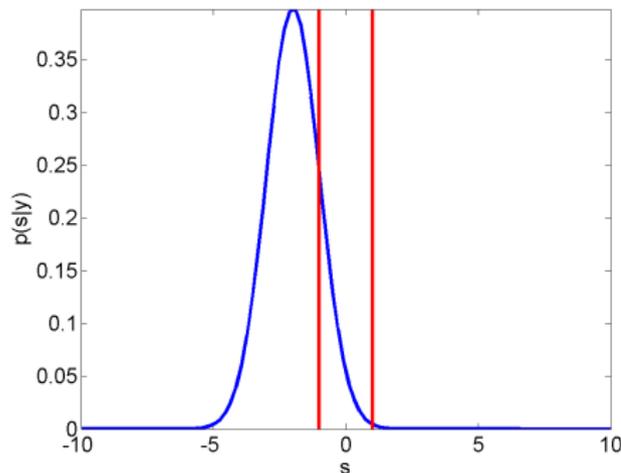
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## Weakly positively activated voxel



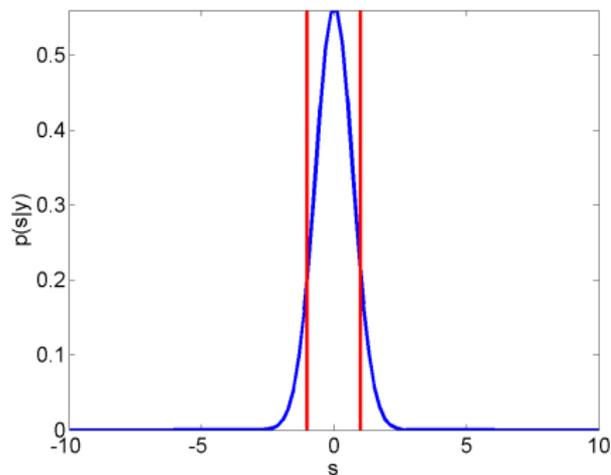
$$p_{posact} = 0.69, p_{negact} = 0.01, p_{notact} = 0.3$$

## Weakly negatively activated voxel



$$p_{posact} = 0.00, p_{negact} = 0.84, p_{notact} = 0.16$$

## Weakly not activated voxel



$$p_{posact} = 0.16, p_{negact} = 0.16, p_{notact} = 0.68$$

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# fMRI example - Odds Ratios

Define Activated = positive or negative

$$\rho_{act} = \rho_{posact} + \rho_{negact}$$

Activated odds

$$R_{act} = \frac{\rho_{act}}{1 - \rho_{act}}$$

Deactivated odds

$$R_{notact} = \frac{\rho_{notact}}{1 - \rho_{notact}}$$

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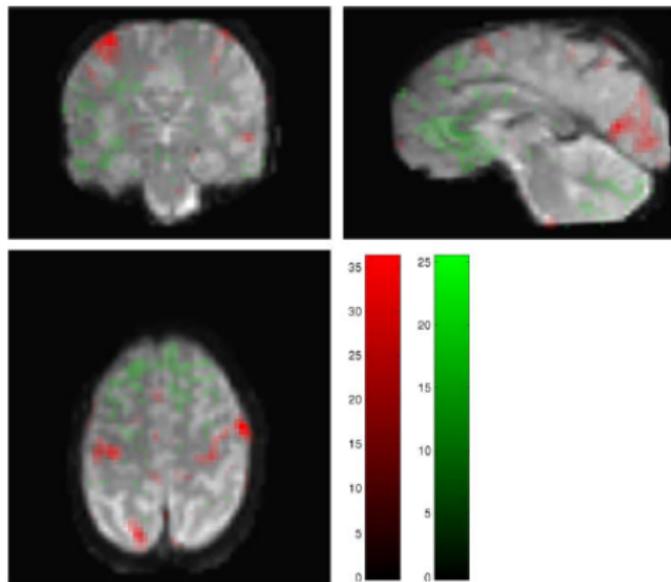
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# fMRI example - Finger Tapping

$\log R_{act}$  (Red) and  $\log R_{notact}$  (Green)



Finger tapping task by Joerg Magergurth et al. (ISMRM, 2013). Only plot voxels for which  $\log R \geq 10$ .

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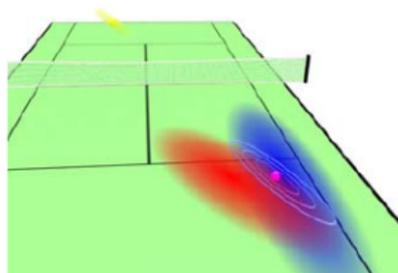
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# Augmented Form



The posterior over  $w$

$$S_w^{-1} = X^T C_y^{-1} X + C_w^{-1}$$
$$m_w = S_w (X^T C_y^{-1} y + C_w^{-1} \mu_w)$$

can also be written in a more compact form.

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This compact form is

$$\begin{aligned}S_w^{-1} &= \bar{X}^T V^{-1} \bar{X} \\ m_w &= S_w (\bar{X}^T V^{-1} \bar{y})\end{aligned}$$

where

$$\begin{aligned}\bar{X} &= \begin{bmatrix} X \\ I_p \end{bmatrix} \\ V &= \begin{bmatrix} C_y & 0 \\ 0 & C_w \end{bmatrix} \\ \bar{y} &= \begin{bmatrix} y \\ \mu_w \end{bmatrix}\end{aligned}$$

where we've augmented the data matrix with prior expectations;  $\bar{y}$  is  $(d + p) \times 1$  and  $\bar{X}$  is  $(d + p) \times p$ .

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Estimation in a Bayesian GLM is therefore equivalent to Maximum Likelihood estimation (ie. for IID covariances this is the same as Weighted Least Squares) with *augmented* data.

$$m_w = (\bar{X}^T V^{-1} \bar{X})^{-1} \bar{X}^T V^{-1} \bar{y}$$

Prior beliefs can be thought of as extra data points.

# MAP Learning

The posterior density is given by Bayes rule

$$p(w|y) = \frac{p(y|w)p(w)}{p(y)}$$

The Maximum A Posterior (MAP) estimate is given by

$$\hat{w} = \arg \max_w p(w|y)$$

Because the maxima of  $\log[x]$  is the same as the maximum of  $x$  we can also write

$$\hat{w} = \arg \max_w L(y, w)$$

where

$$L = \log[p(y|w)p(w)]$$

is the joint log likelihood. For Linear Gaussian models MAP parameters are equivalent to the posterior mean.

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# MAP Learning and regularised least squares

With

$$\begin{aligned}p(y|w) &= \mathcal{N}(y; Xw, \lambda_1^{-1}I) \\ p(w) &= \mathcal{N}(w; 0, \lambda_2^{-1}C_w)\end{aligned}$$

we have

$$\begin{aligned}L(y, w) &= \log[p(y|w)p(w)] \\ &= -\frac{\lambda_1}{2}(y - Xw)^T(y - Xw) - \frac{\lambda_2}{2}w^T C_w^{-1}w\end{aligned}$$

So we are trying to minimise

$$(y - Xw)^T(y - Xw) + \frac{\lambda_2}{\lambda_1}w^T C_w^{-1}w$$

a data-dependent error term and a regularisation term

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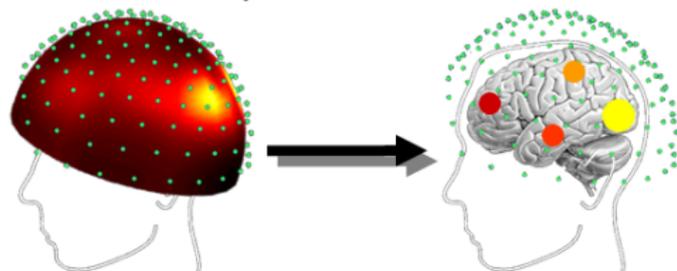
# MEG Source Reconstruction

MEG Source Reconstruction is achieved through inversion of the linear model

$$y = Xw + e$$

$$(d \times 1) = (d \times p)(p \times 1) + (d \times 1)$$

for MEG data,  $y$  with  $d$  sensors and  $p$  potential sources,  $w$ , lying perpendicular to the cortical surface. The lead field matrix is specified by  $X$ . For our example we have  $d = 274$  and  $p = 8192$ .



The above equation is for a single time point.

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Likelihood

$$p(y|w) = N(y; Xw, C_y)$$

Prior

$$p(w) = N(w; 0, C_w)$$

We let

$$C_y = \lambda_1 Q_1$$

$$C_w = \lambda_2 Q_2$$

For shrinkage priors  $Q_2 = I_p$ , MAP estimation results in the minimum norm method of source reconstruction. This is implemented in SPM as the 'IID' option

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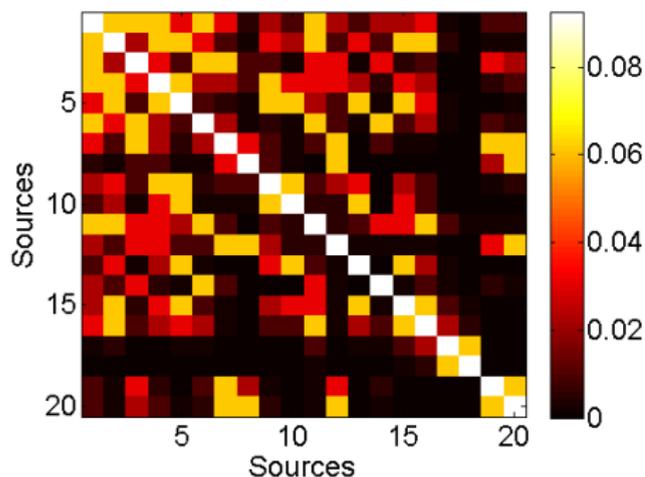
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# Smoothness Priors

For smoothness priors  $Q_2 = KK^T$  corresponding to the operation of a Gaussian smoothing kernel, MAP estimation results something similar to the Low Resolution Tomography (LORETA) method.



This is implemented in SPM as the 'COH' option. Note, these are not location priors.

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# Posterior Density

From earlier we have

$$\begin{aligned}S_w^{-1} &= X^T C_y^{-1} X + C_w^{-1} \\ m_w &= S_w X^T C_y^{-1} y\end{aligned}$$

However,  $S_w$  is  $p \times p$  with  $p = 8192$  so cannot be inverted easily. But we can use the matrix inversion lemma, also known as the Woodbury identity (Bishop, 2006)

$$(A + BCD)^{-1} = A^{-1} - A^{-1}B(C^{-1} + DA^{-1}B)^{-1}DA^{-1}$$

to ensure that only  $d \times d$  matrices need inverting. See 'Bayesian MEG' notes on website.

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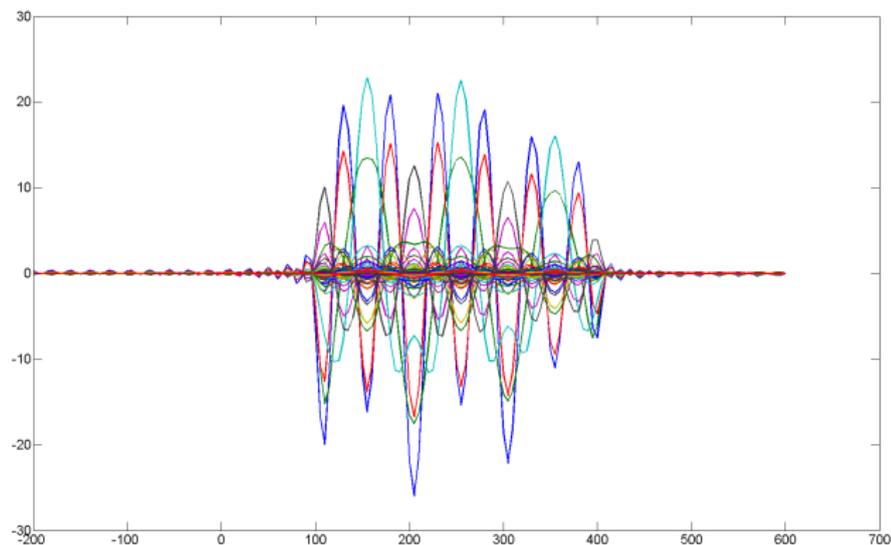
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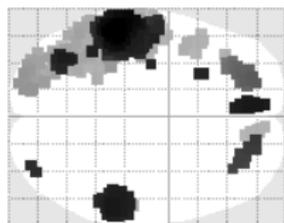
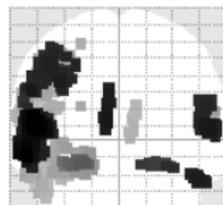
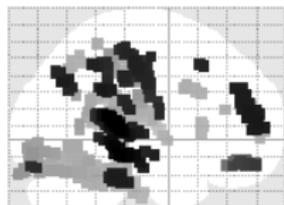
# Simulation

Two sinusoidal sources were placed in bilateral auditory cortex and produced this MEG data (Barnes, 2010), comprising  $d = 274$  time series (butterfly plot)



# LORETA

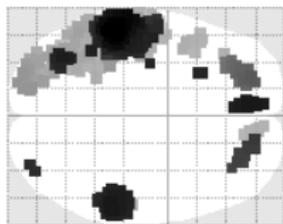
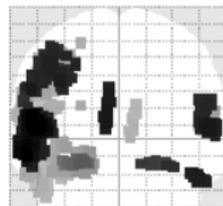
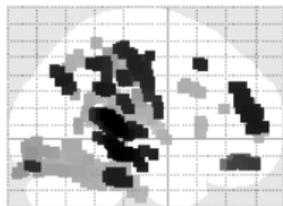
We fix  $\lambda_1 = 1$ . Here we set  $\lambda_2 = 0.01$ .



This shows the posterior mean activity for the 500 dipoles with the greatest power (over peristimulus time)

# LORETA

We fix  $\lambda_1 = 1$ . Here we set  $\lambda_2 = 0.01$ .



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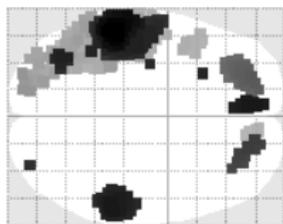
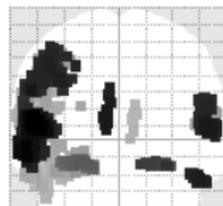
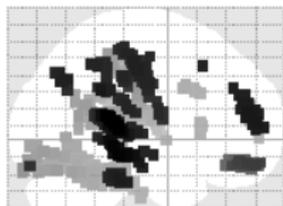
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# LORETA

We fix  $\lambda_1 = 1$ . Here we set  $\lambda_2 = 0.1$ .



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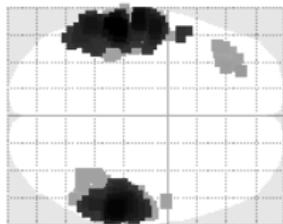
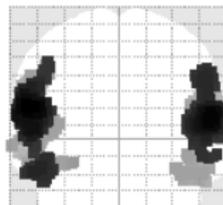
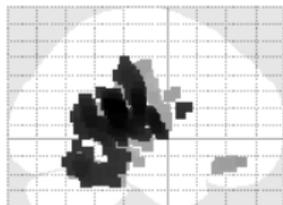
MAP Learning

MEG Source  
Reconstruction

References

# LORETA

We fix  $\lambda_1 = 1$ . Here we set  $\lambda_2 = 1$ .



Maximum  
Likelihood

Linear Models

fMRI analysis

Bayesian Linear  
Models

fMRI example

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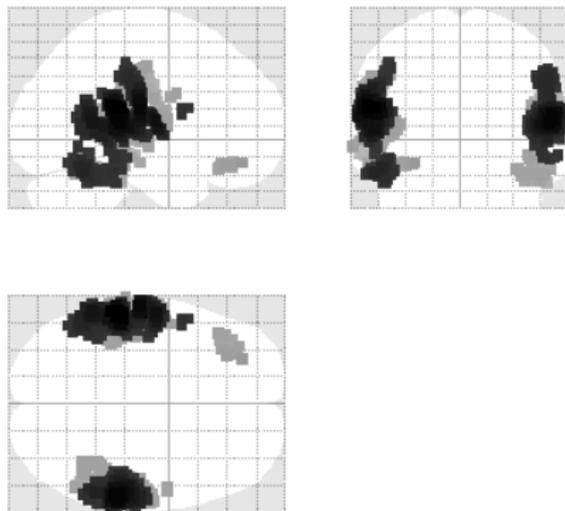
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# LORETA

We fix  $\lambda_1 = 1$ . Here we set  $\lambda_2 = 1$ .



Use Empirical Bayes to optimise  $\lambda_2$  or multiple hyperparameters.

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