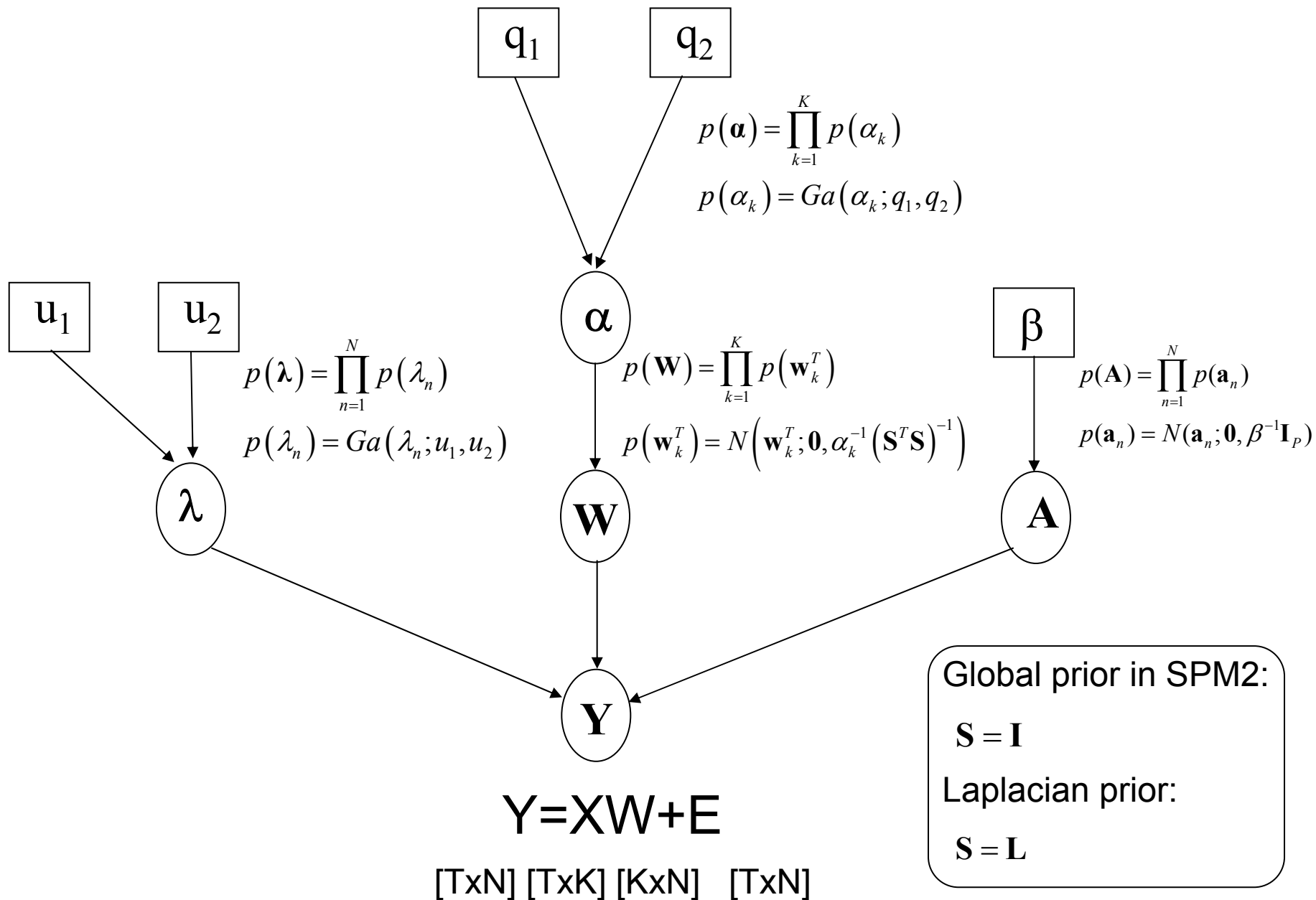


PPMs with Spatial Priors

Will, Nelson, Karl

GLM-AR(p) models (+Stefan) with spatial priors
on regression/AR coefficients for single-subject fMRI



Variational Bayes

In prior, \mathbf{W} factorises over k :

$$p(\mathbf{W}, \mathbf{A}, \boldsymbol{\lambda}, \boldsymbol{\alpha}) = \left(\prod_k p(\mathbf{w}_k | \alpha_k) p(\alpha_k | q_1, q_2) \right) \left(\prod_n p(\mathbf{a}_n | \beta) p(\lambda_n | u_1, u_2) \right)$$

In *chosen* approximate posterior, \mathbf{W} factorises over n :

$$q(\mathbf{W}, \mathbf{A}, \boldsymbol{\lambda}, \boldsymbol{\alpha} | \mathbf{Y}) = \left(\prod_k q(\alpha_k | \mathbf{Y}) \right) \left(\prod_n q(\mathbf{w}_n | \mathbf{Y}) q(\mathbf{a}_n | \mathbf{Y}) q(\lambda_n | \mathbf{Y}) \right)$$

Update SS of approximate posterior to maximise (lower bound on) evidence

$$L = \log p(Y)$$

$$= F + KL[q(\boldsymbol{\theta} | Y), p(\boldsymbol{\theta} | Y)]$$

Updating approximate posterior

Regression coefficients

$$\begin{aligned}q(\mathbf{w}_n) &= N(\mathbf{w}_n; \hat{\mathbf{w}}_n, \hat{\Sigma}_n) \\ \hat{\mathbf{w}}_n &= \hat{\Sigma}_n (\bar{\lambda}_n \tilde{\mathbf{b}}_n^T + \mathbf{r}_n) \\ \hat{\Sigma}_n &= (\bar{\lambda}_n \tilde{\mathbf{A}}_n + \mathbf{B}_{nn})^{-1} \\ \mathbf{B} &= \mathbf{H} (\text{diag}[\boldsymbol{\alpha}] \otimes \mathbf{S}^T \mathbf{S}) \mathbf{H}^T \\ \mathbf{r}_n &= - \sum_{i=1, i \neq n}^N \mathbf{B}_{ni} \hat{\mathbf{w}}_i\end{aligned}$$

Spatial precisions

$$\begin{aligned}q(\boldsymbol{\alpha}) &= \prod_{k=1}^K q(\alpha_k) \\ q(\alpha_k) &= Ga(\alpha_k; \mathbf{g}_k, h_k) \\ \frac{1}{\mathbf{g}_k} &= \frac{1}{2} \left[\text{Tr}(\hat{\Sigma}_k \mathbf{S}^T \mathbf{S}) + \hat{\mathbf{w}}_k^T \mathbf{S}^T \mathbf{S} \hat{\mathbf{w}}_k \right] + \frac{1}{q_1} \\ h_k &= \frac{N}{2} + q_2 \\ \bar{\alpha}_k &= \mathbf{g}_k h_k\end{aligned}$$

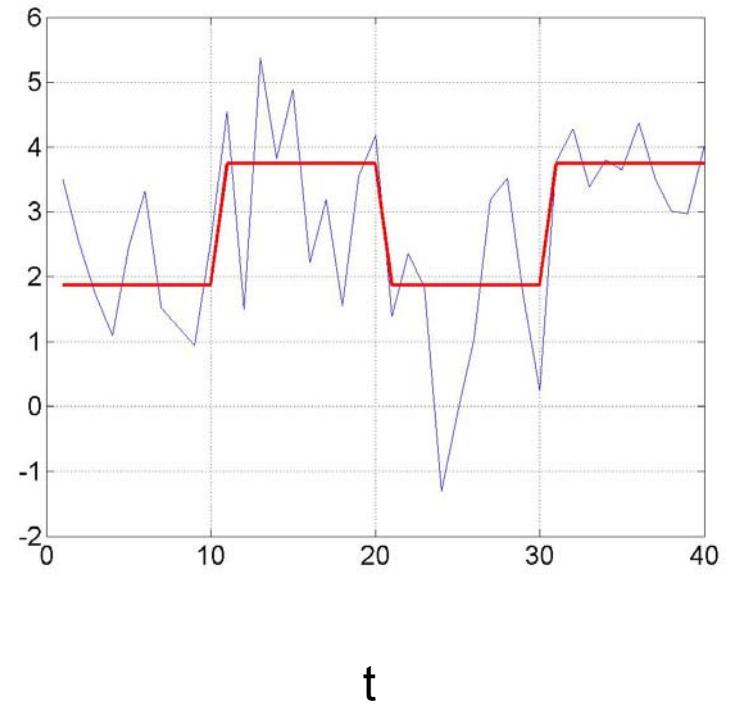
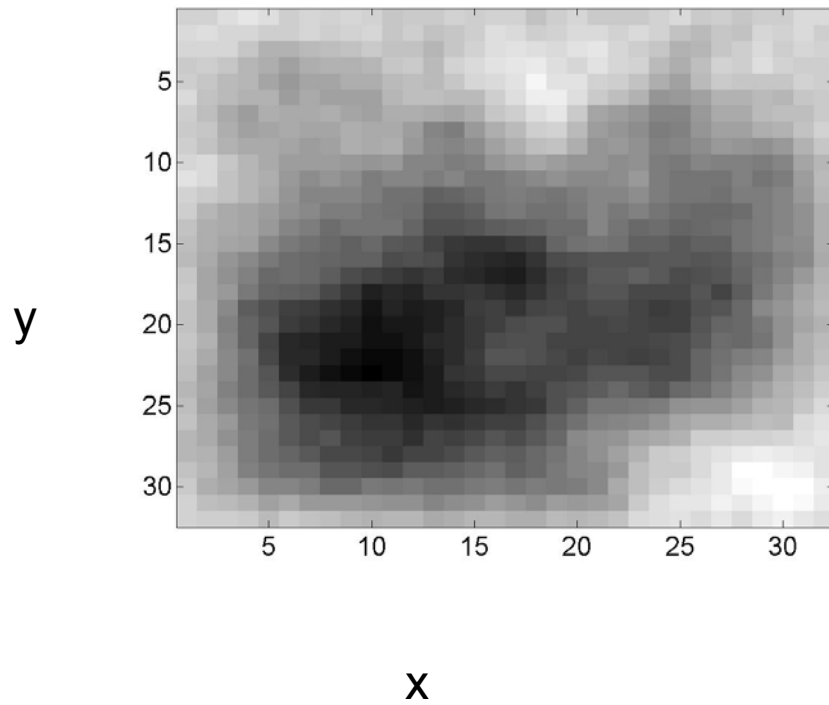
AR coefficients

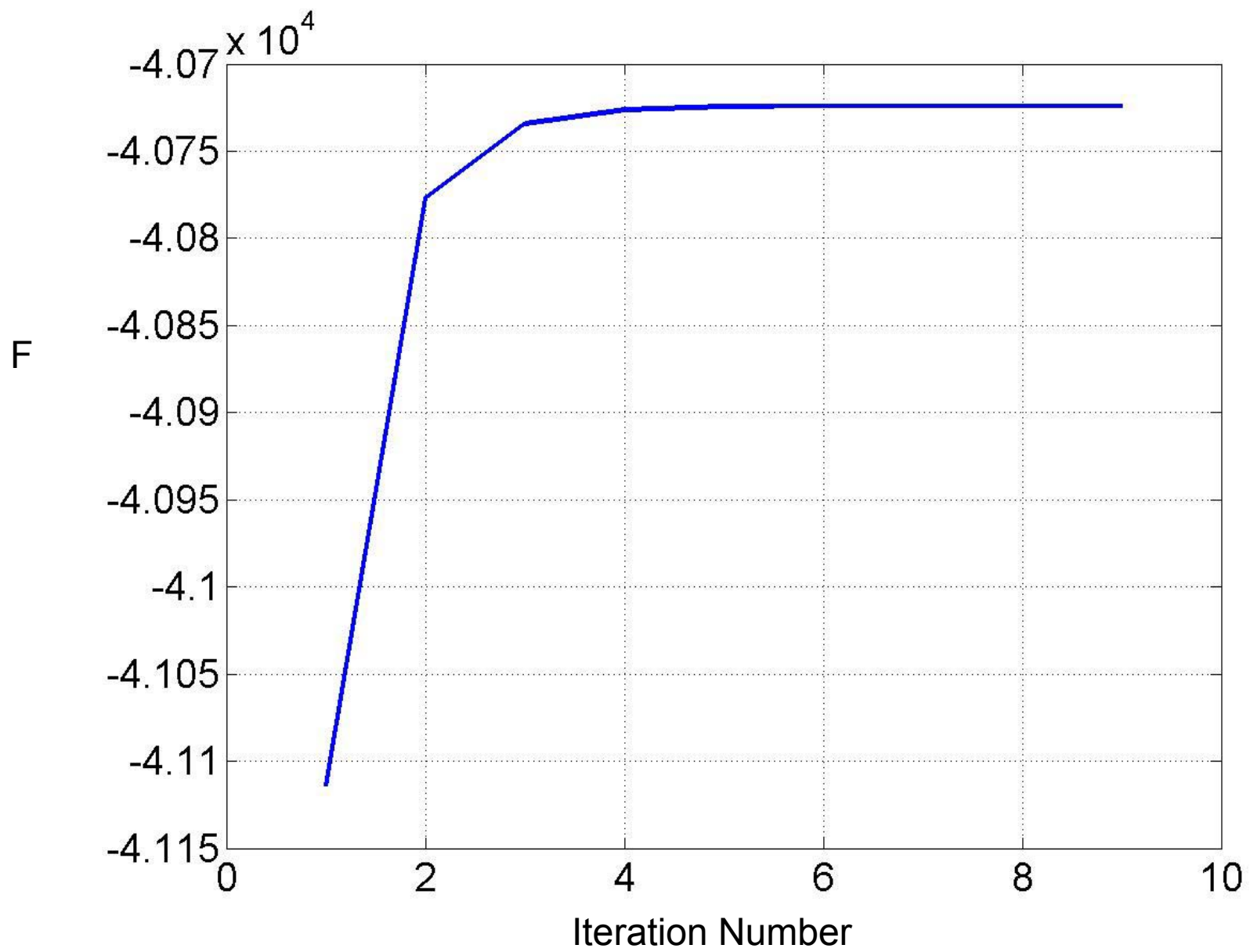
$$\begin{aligned}q(\mathbf{a}_n) &= N(\mathbf{a}_n; \mathbf{m}_n, \mathbf{V}_n) \\ \mathbf{V}_n &= (\lambda_n \tilde{\mathbf{C}}_n + \beta \mathbf{I}_p)^{-1} \\ \mathbf{m}_n &= \lambda_n \tilde{\mathbf{D}}_n \mathbf{V}_n\end{aligned}$$

Observation noise

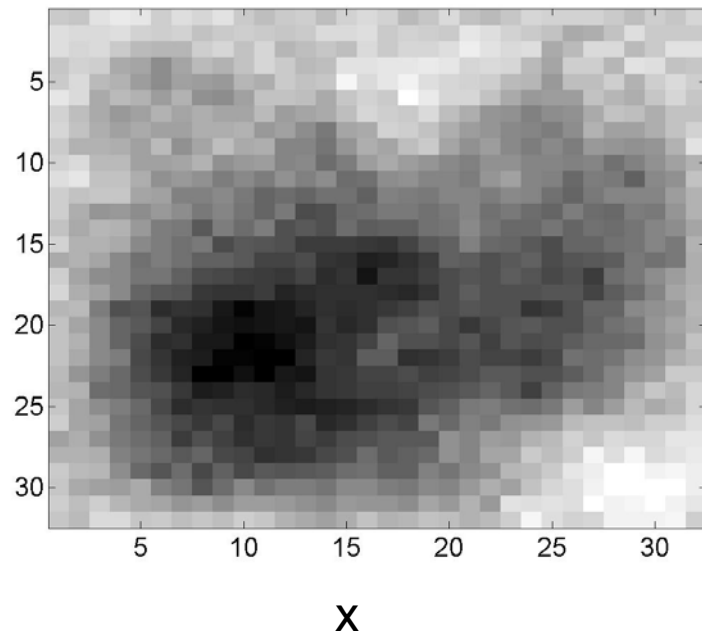
$$\begin{aligned}q(\lambda_n) &= Ga(\lambda_n; b_n, c_n) \\ \frac{1}{b_n} &= \frac{\tilde{G}_n}{2} + \frac{1}{u_1} \\ c_n &= \frac{T}{2} + u_2\end{aligned}$$

Synthetic Data 1 : from Laplacian Prior



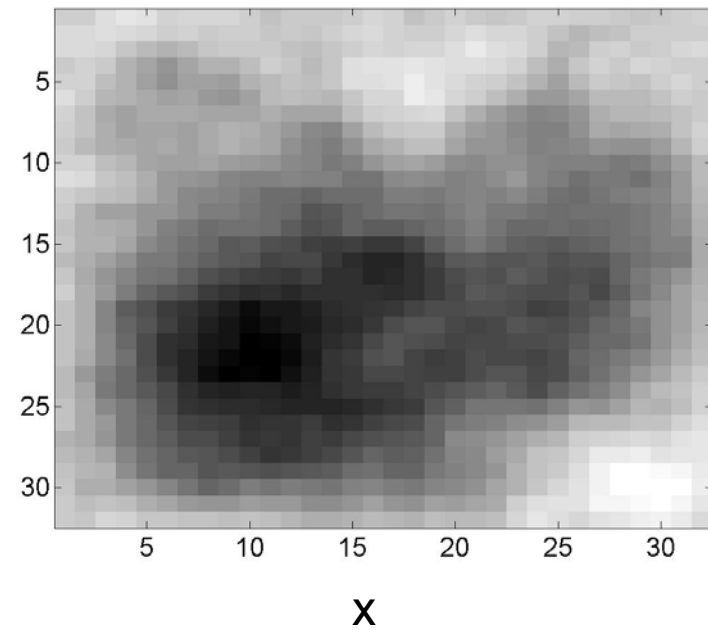


Least Squares



Coefficients = 1024

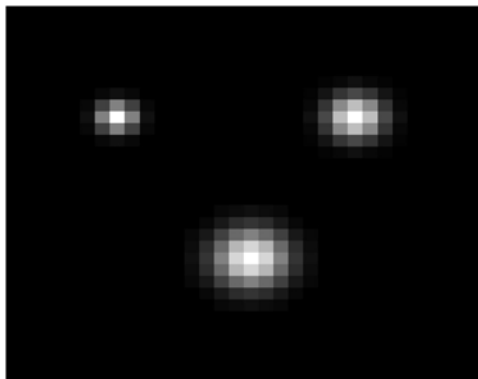
VB – Laplacian Prior



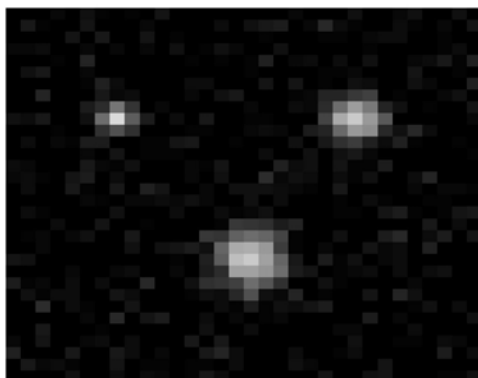
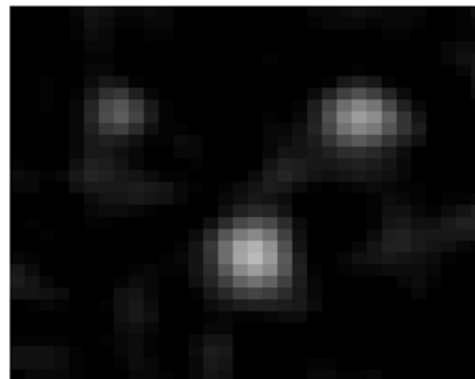
'Coefficient RESELS' = 366

Synthetic Data II : blobs

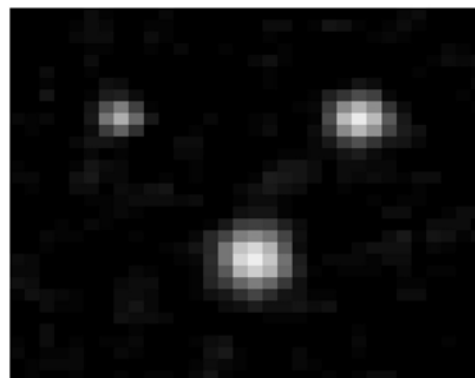
True



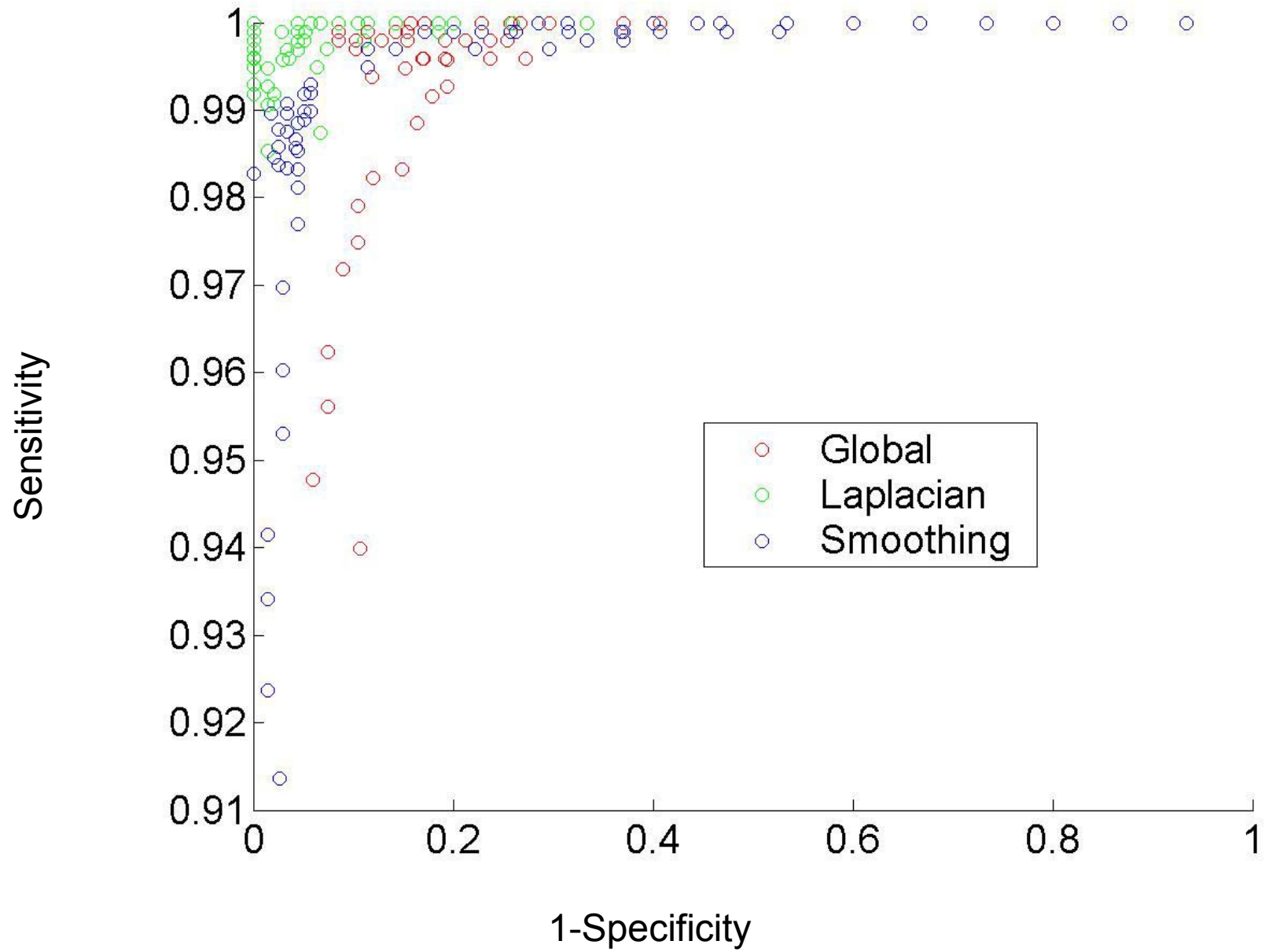
Smoothing



Global prior

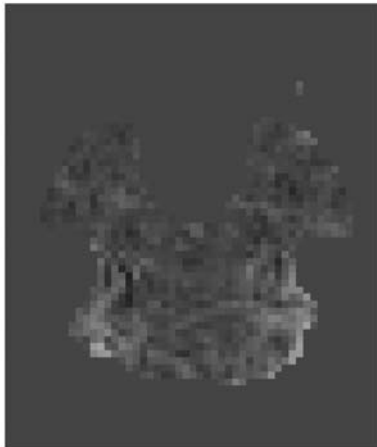
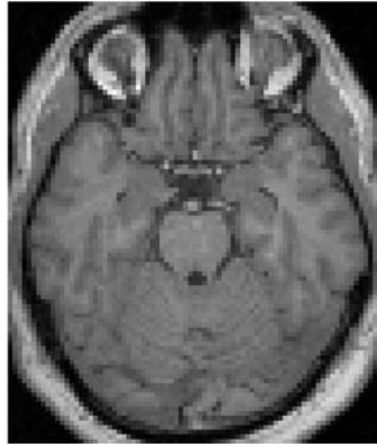


Laplacian prior

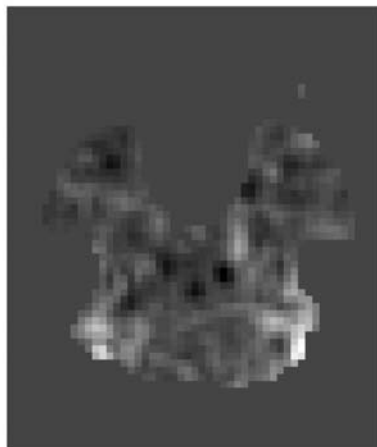


Event-related fMRI: Faces versus chequerboard

Smoothing



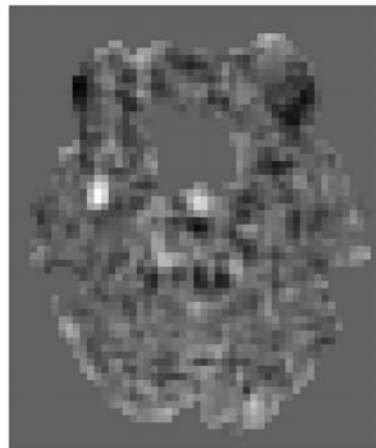
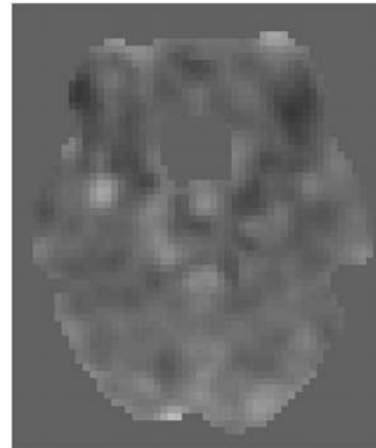
Global prior



Laplacian Prior

Event-related fMRI: Familiar faces versus unfamiliar faces

Smoothing



Global prior

Laplacian Prior

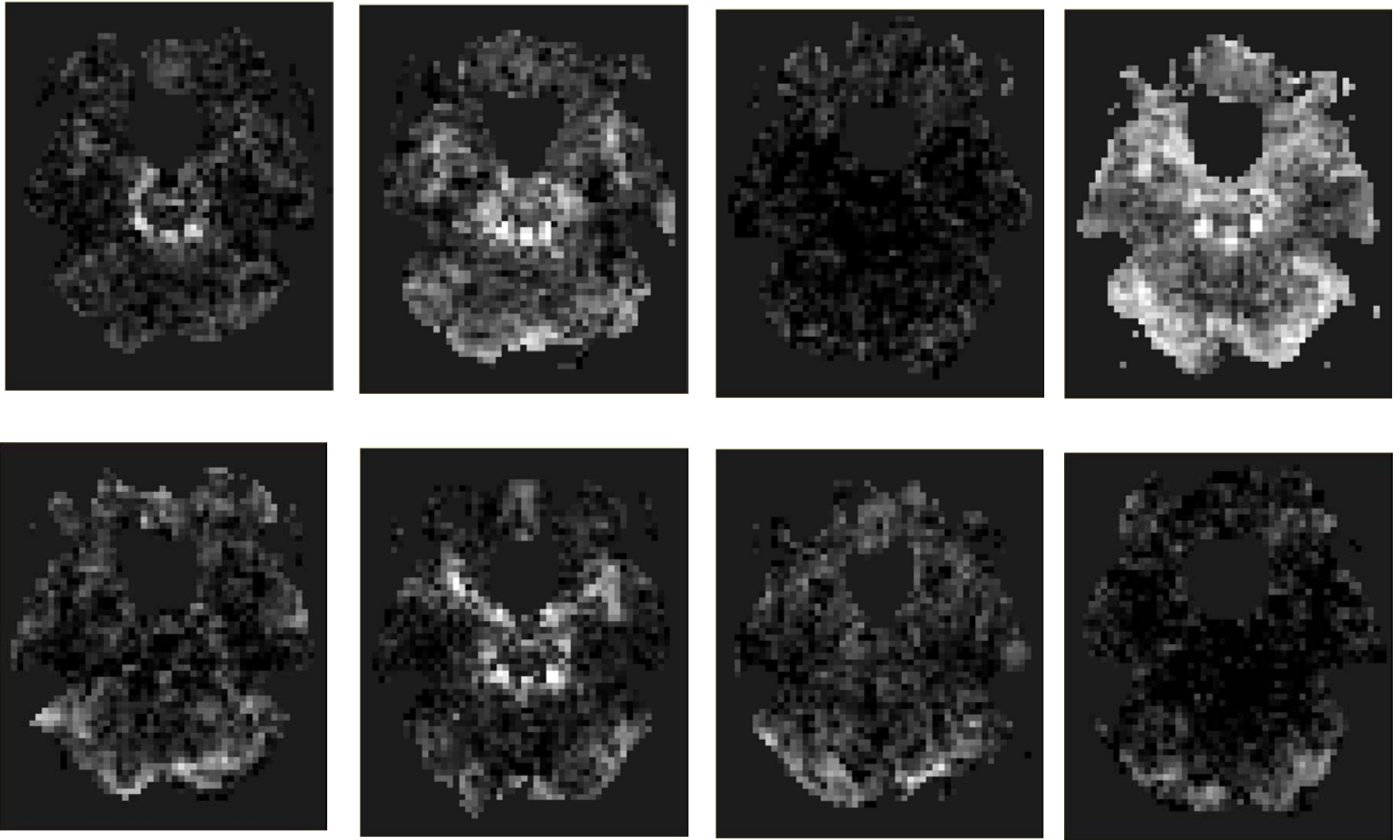
Summary

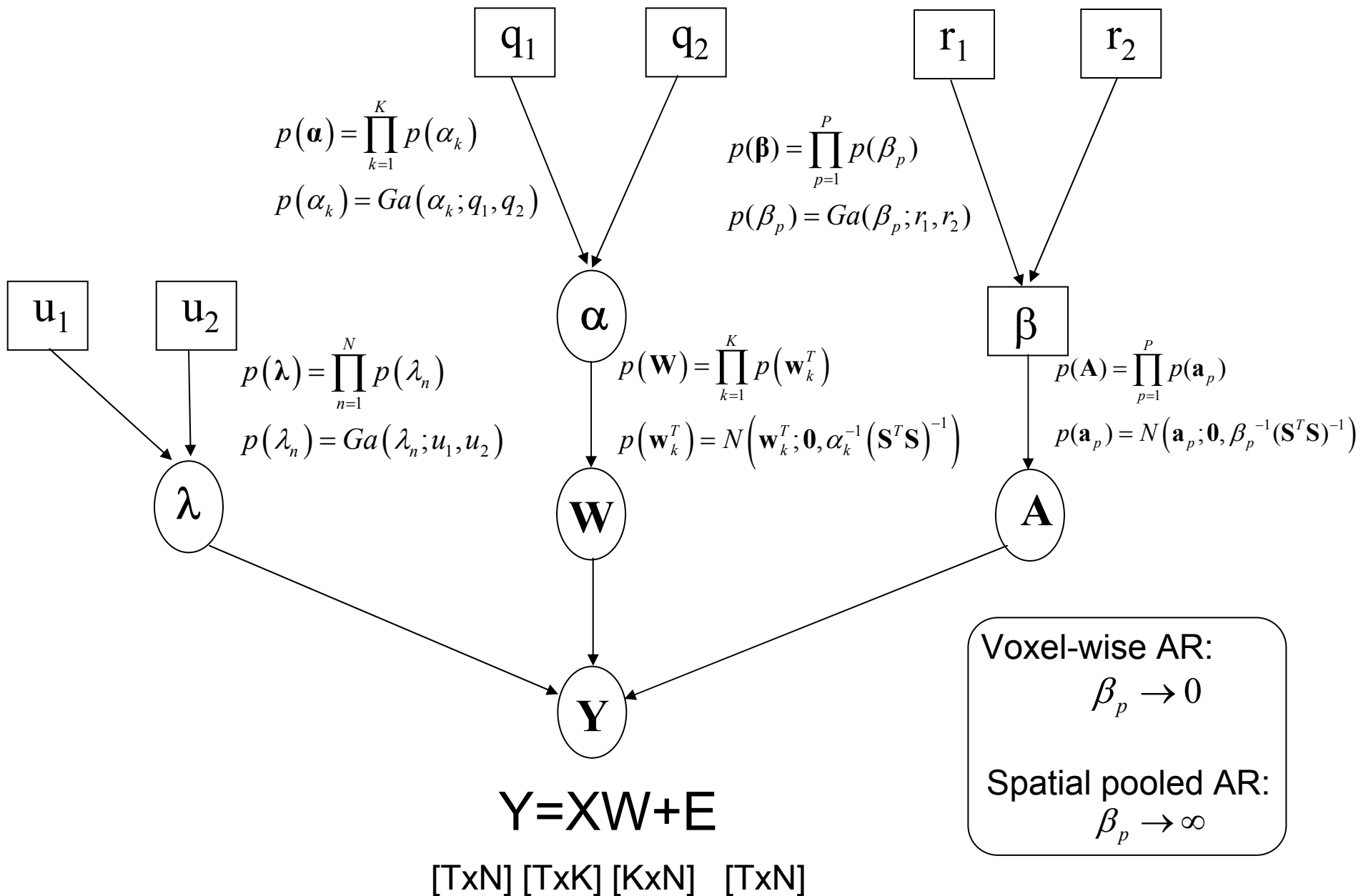
- No need to smooth data at 1st level
- Greater sensitivity
- Implementation in parallel to non-Bayesian methods – `spm/devel`
- 5-10 minutes per slice
- Model comparison of signal and noise models for single/multiple regions/slices

The future

- Laplacian priors for AR coefficients
- Mixture priors
- Wavelet priors
- 2nd level noise models

Maps of AR(1) coefficient





Updating approximate posterior

Regression coefficients

$$\begin{aligned}
 q(\mathbf{w}_n) &= N(\mathbf{w}_n; \hat{\mathbf{w}}_n, \hat{\Sigma}_n) \\
 \hat{\mathbf{w}}_n &= \hat{\Sigma}_n (\bar{\lambda}_n \tilde{\mathbf{b}}_n^T + \mathbf{r}_n) \\
 \hat{\Sigma}_n &= (\bar{\lambda}_n \tilde{\mathbf{A}}_n + \mathbf{B}_{nn})^{-1} \\
 \mathbf{B} &= \mathbf{H}(\text{diag}[\boldsymbol{\alpha}] \otimes \mathbf{S}^T \mathbf{S}) \mathbf{H}^T \\
 \mathbf{r}_n &= - \sum_{i=1, i \neq n}^N \mathbf{B}_{ni} \hat{\mathbf{w}}_i
 \end{aligned}$$

AR coefficients

$$\begin{aligned}
 q(\mathbf{a}_n) &= N(\mathbf{a}_n; \mathbf{m}_n, \mathbf{V}_n) \\
 \mathbf{V}_n &= (\lambda_n \tilde{\mathbf{C}}_n + \mathbf{J}_{nn})^{-1} \\
 \mathbf{m}_n &= \mathbf{V}_n (\lambda_n \tilde{\mathbf{D}}_n + \mathbf{j}_n) \\
 \mathbf{J} &= \mathbf{H}(\text{diag}(\bar{\boldsymbol{\beta}}) \otimes \mathbf{S}^T \mathbf{S}) \mathbf{H}^T \\
 \mathbf{j}_n &= - \sum_{i=1, i \neq n}^N \mathbf{J}_{ni} \mathbf{m}_i
 \end{aligned}$$

Spatial precisions for \mathbf{W}

$$\begin{aligned}
 q(\boldsymbol{\alpha}) &= \prod_{k=1}^K q(\alpha_k) \\
 q(\alpha_k) &= Ga(\alpha_k; \mathbf{g}_k, h_k) \\
 \frac{1}{\mathbf{g}_k} &= \frac{1}{2} \left[\text{Tr}(\hat{\Sigma}_k \mathbf{S}^T \mathbf{S}) + \hat{\mathbf{w}}_k^T \mathbf{S}^T \mathbf{S} \hat{\mathbf{w}}_k \right] + \frac{1}{q_1} \\
 h_k &= \frac{N}{2} + q_2 \\
 \bar{\alpha}_k &= \mathbf{g}_k h_k
 \end{aligned}$$

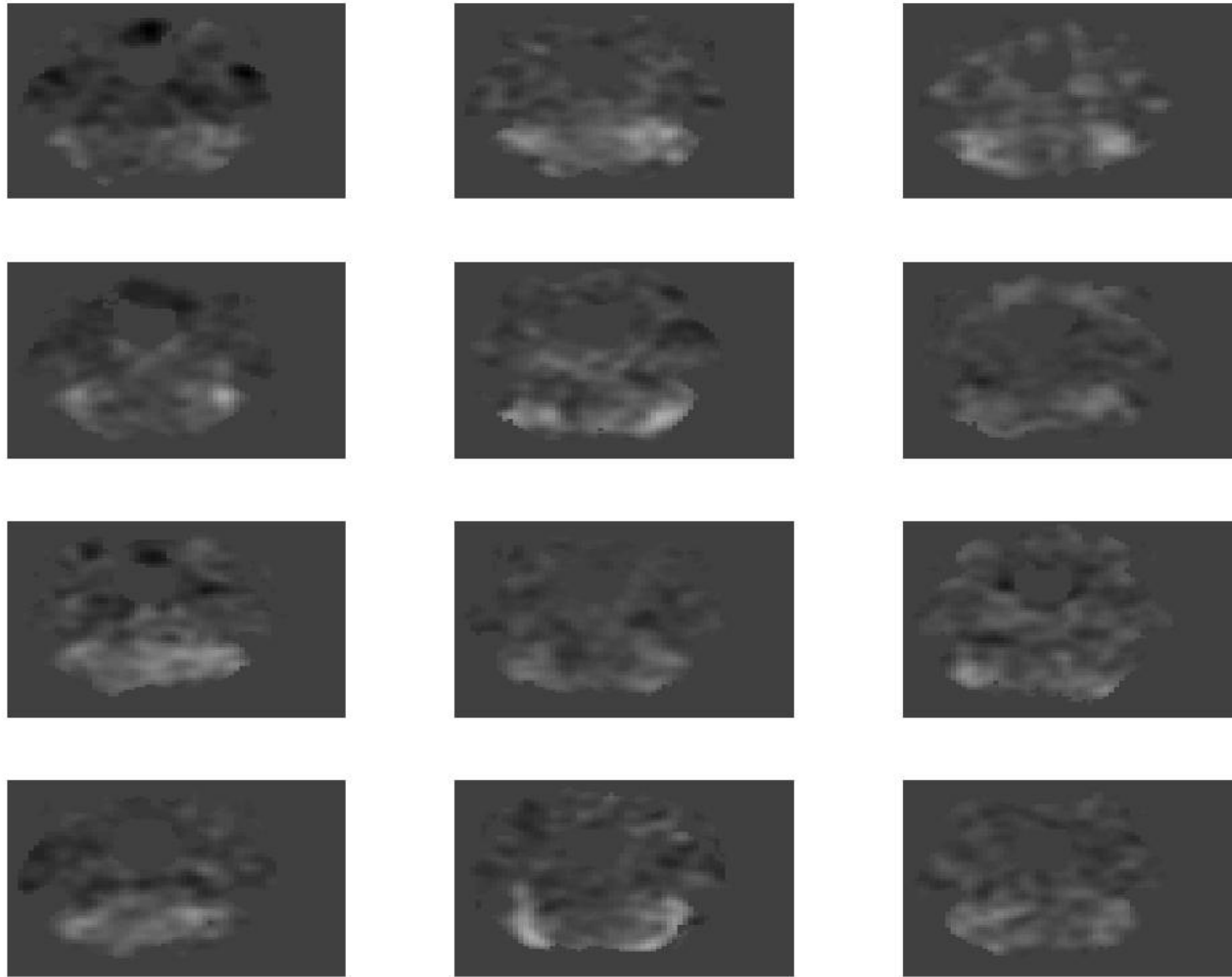
Spatial precisions for \mathbf{A}

$$\begin{aligned}
 q(\boldsymbol{\beta}) &= \prod_{p=1}^P q(\beta_p) \\
 q(\beta_p) &= Ga(\beta_p; r_{1p}, r_{2p}) \\
 \frac{1}{r_{1p}} &= \frac{1}{2} \left(\text{Tr}(\mathbf{V}_p \mathbf{S}^T \mathbf{S}) + \mathbf{m}_p^T \mathbf{S}^T \mathbf{S} \mathbf{m}_p \right) + \frac{1}{r_1} \\
 r_{2p} &= \frac{P}{2} + r_2 \\
 \bar{\beta}_p &= r_{1p} r_{2p}
 \end{aligned}$$

Observation noise

$$\begin{aligned}
 q(\lambda_n) &= Ga(\lambda_n; b_n, c_n) \\
 \frac{1}{b_n} &= \frac{\tilde{G}_n}{2} + \frac{1}{u_1} \\
 c_n &= \frac{T}{2} + u_2
 \end{aligned}$$

Gaussian smoothing



Wavelet smoothing

